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Liquid in a wedge...

Natural occurrence: feeding phalarope shorebird^[1]



Theoretical equilibrium: energy based model^[2]

$$U = A_{SL}\gamma_{SL} + A_{LG}\gamma_{LG} + A_{SG}\gamma_{SG}$$

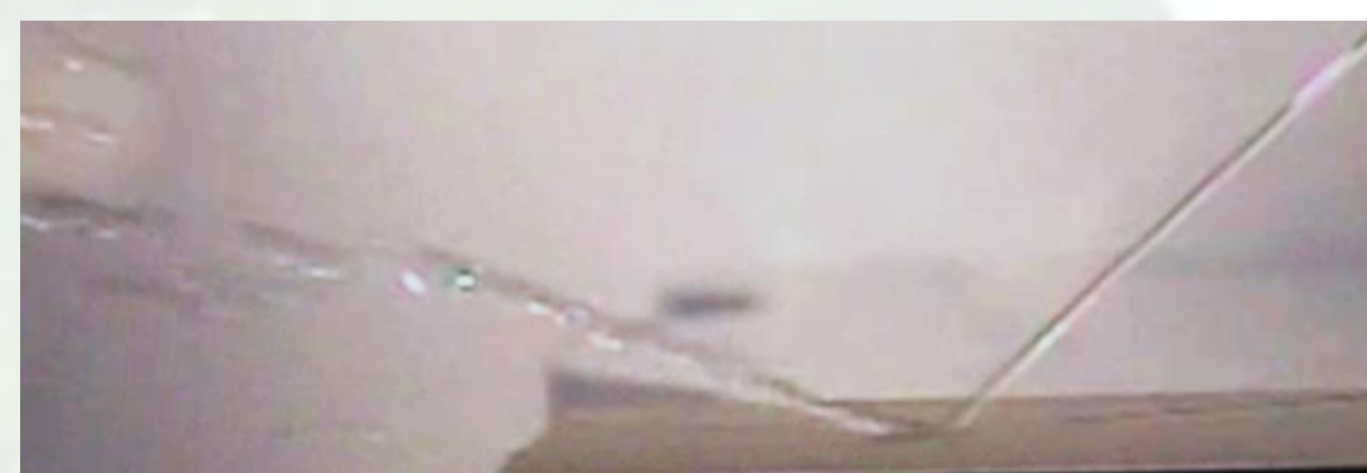
$$= \gamma_{SG}(A_{SL} + A_{SG}) + \gamma_{LG}(A_{LG} - A_{SL} \cos \theta)$$

$$\vec{F}_L = -\vec{\nabla}U = \gamma_{LG} \left(\cos \theta \frac{dA_{SL}}{dx} - \frac{dA_{LG}}{dx} \right) \cdot \vec{i}$$

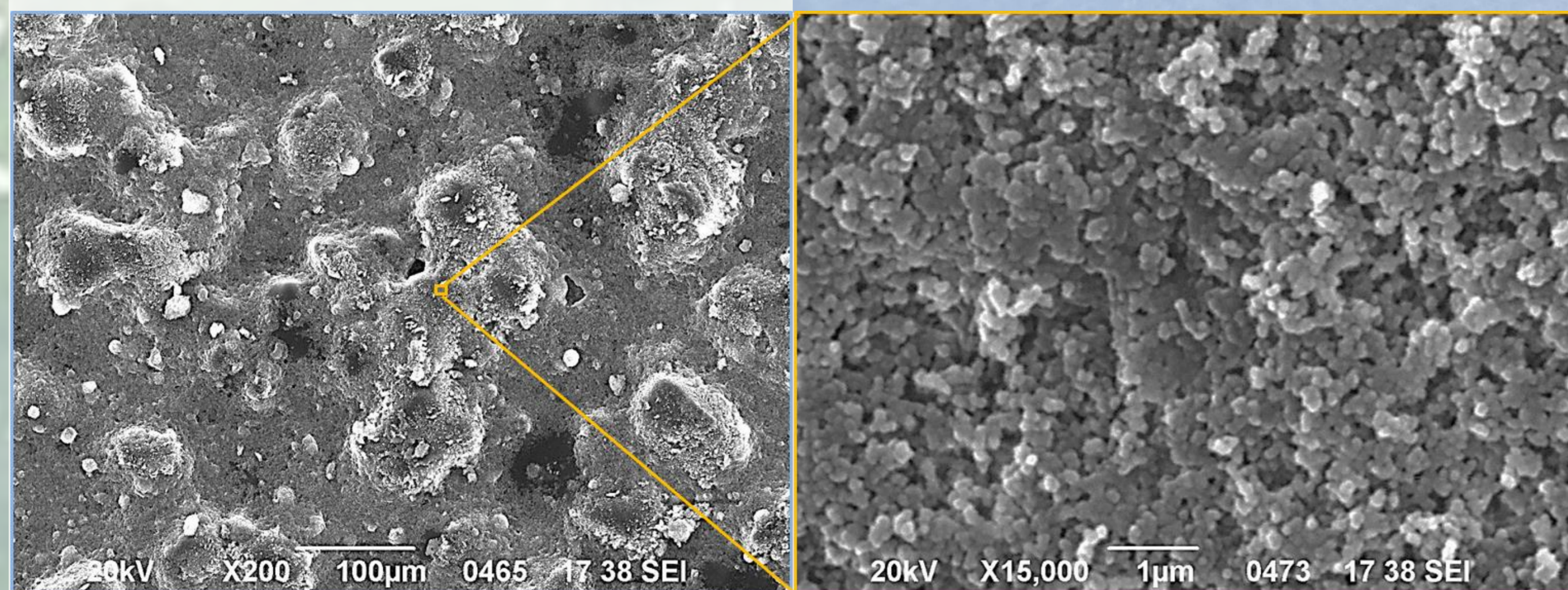
... And superhydrophobic surfaces

Super-non-wetting regime (lotus leaf effect)^[3, 4, 5]

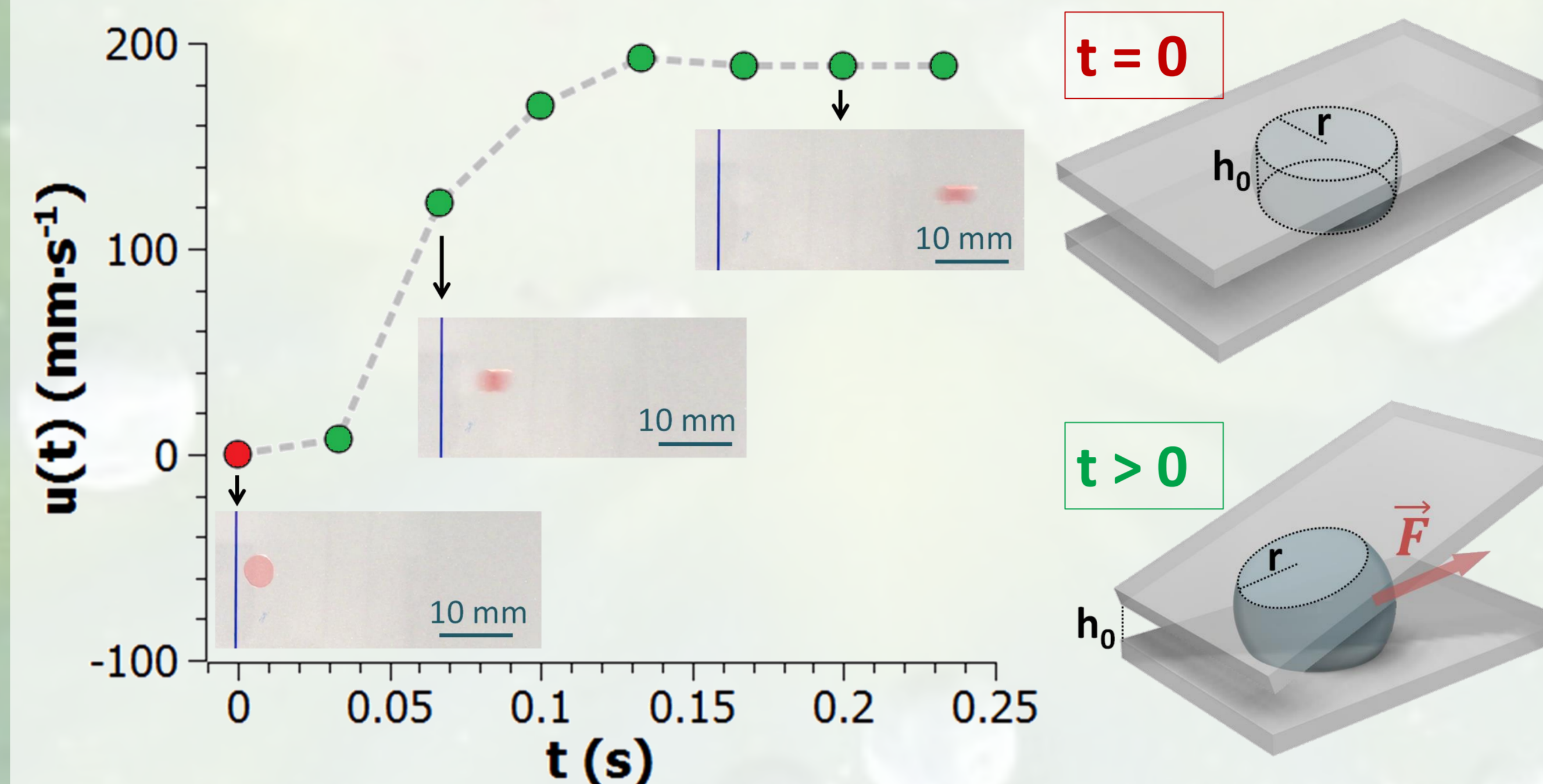
- Contact angle $\theta > 150^\circ$
- Cassie-Baxter model^[4]



Surface fabrication
Using NeverWet^[5] for
the present study



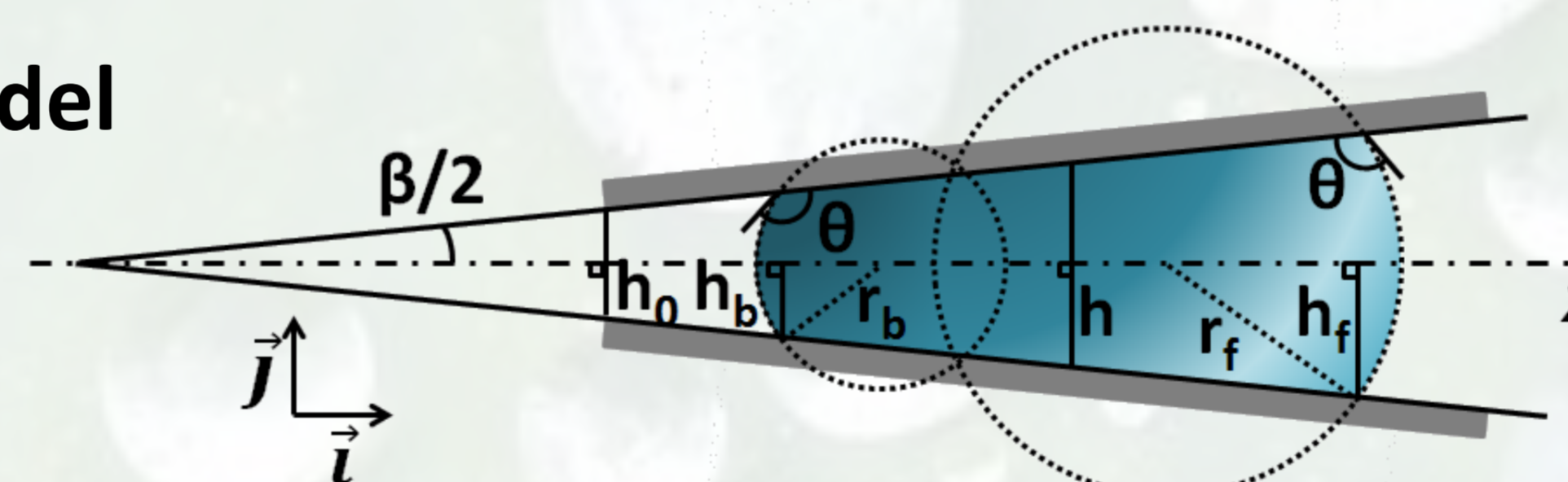
Self-propulsion behaviour...



... Tailored by the system geometry

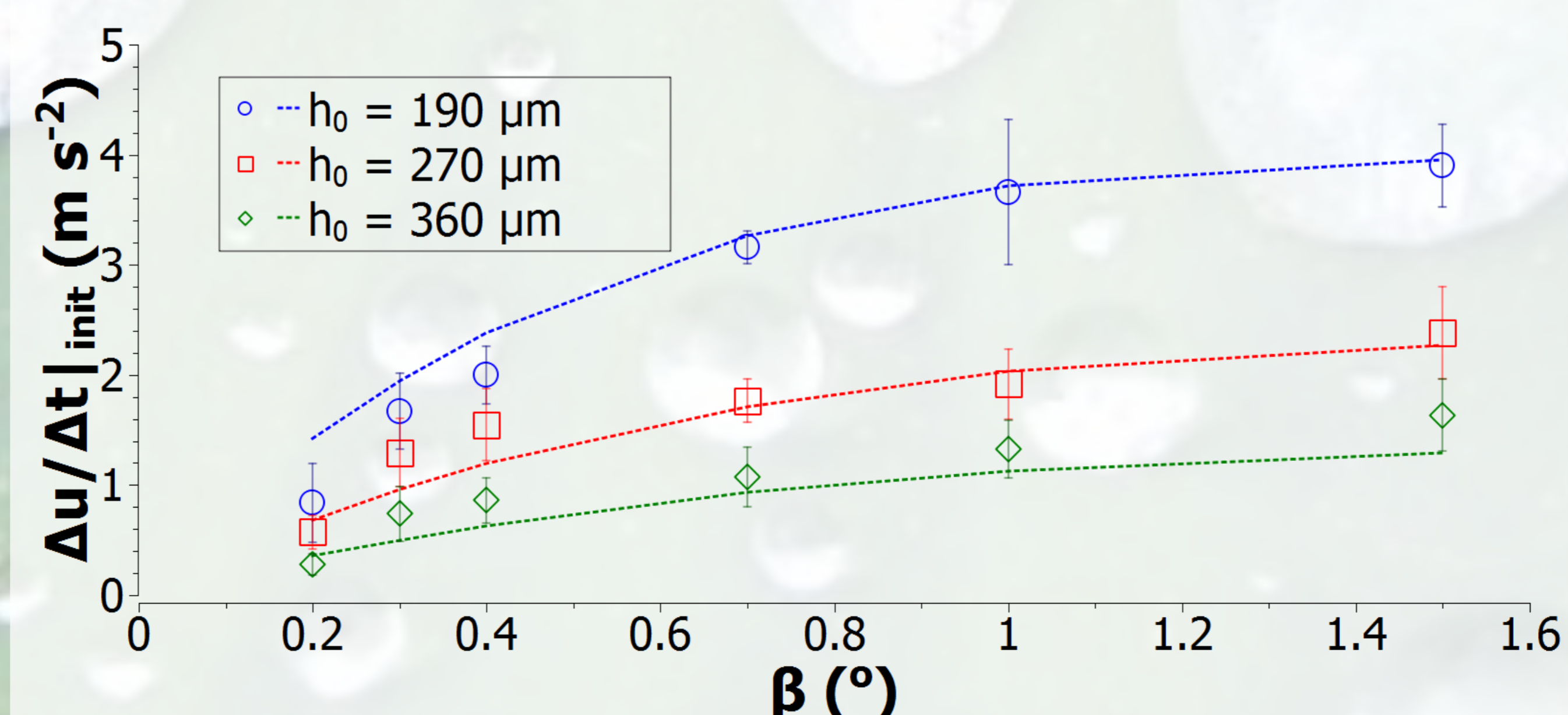
Simplified model

for $0^\circ < \beta < 2^\circ$
($\cos \beta \approx 1$)

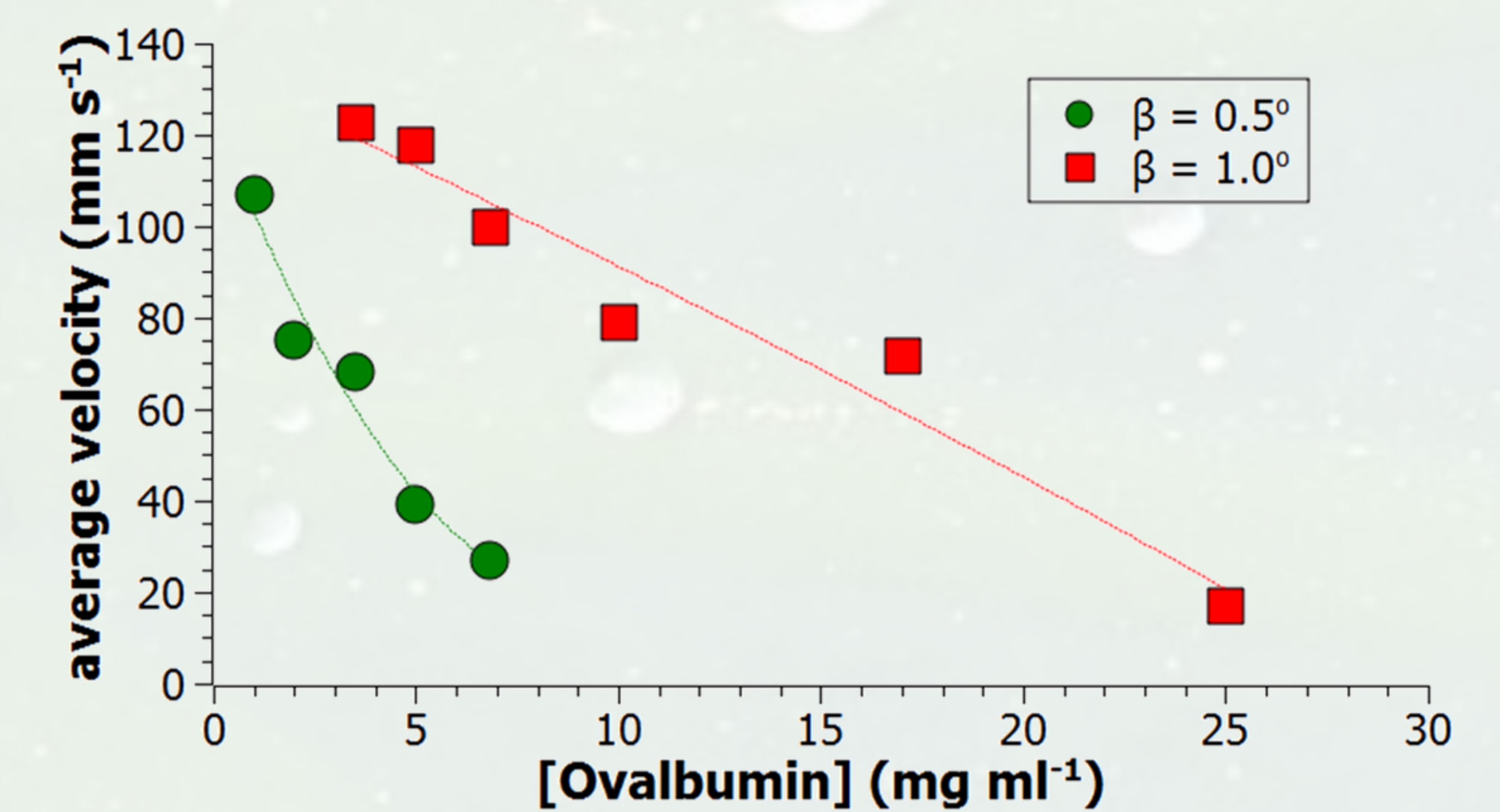


$$\vec{F}_L = -\gamma_{LG} \left(V \cos \theta \frac{\cot(\frac{\beta}{2})}{x^2} + \sqrt{\frac{2\pi}{x}} V \tan(\frac{\beta}{2}) \right) \cdot \vec{i}$$

Acceleration: model (lines) vs experiment (points)



Actuation of protein-laden droplets



Further development potential

- Droplet generation and transport
- Combining self propulsion and electrowetting for enhanced control over actuation
- Digital microfluidics using localised deflection of flexible membranes

Conclusion

Self-propulsion of liquid in non-wetting wedges offers interesting development perspectives for handling biomaterial-laden droplets in lab-on-a-chip devices

References

- [1] Prakash, Quéré and Bush (2008) *Science* 320 931-934 [2] Ruiz-Gutiérrez, Semperebon, McHale and Ledesma-Aguilar (2018) *J. Fluid Mech.* 842 26-57 [3] Ensikat, Ditsche-Kuru, Neinhuis and Barthlott (2011) *Beilstein J. of Nanotech.* 2 152-161 [4] Lafuma, and Quéré (2003) *Nature Mater* 2 457-460 [5] Latip, Coudron, McDonnell, Johnston, McCluskey, Day and Tracey (2017) *RSC Advances* 7 49633-49648