

# Quantum protocols for anonymous voting and surveying

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We describe quantum protocols for voting and surveying. A key feature of our schemes is the use of entangled states to ensure that the votes are anonymous and to allow the votes to be tallied. The entanglement is distributed over separated sites; the physical inaccessibility of any one site is sufficient to guarantee the anonymity of the votes. The security of these protocols with respect to various kinds of attack is discussed. We also discuss classical schemes and show that our quantum voting protocol represents a  $N$ -fold reduction in computational complexity, where  $N$  is the number of voters.

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## I. INTRODUCTION

A well-established consequence of the proven security [1] of quantum key distribution is that quantum systems can be used for unconditionally secure classical information transmission. It is widely believed that classical cryptosystems cannot distribute a key such as a one-time pad with unconditional security. Without a one-time pad classical cryptosystems are secure only on condition that insufficient computational resources are available to render them vulnerable. While this assumption is reasonable at the present time, we anticipate that, in the future, quantum computers will be developed which may be used to attack cryptosystems reliant upon either integer factorization or discrete logarithm evaluation using, for example, Shor's algorithm. The security of most common cryptosystems is dependent on the fact that no known efficient classical algorithm exists that can break particular implementations used within the time period for which security is desired. As such, although quantum computation will bring many benefits, it will also be highly disruptive with regard to data security.

For this reason, it is highly probable that, to create cryptographic keys, we will have to turn to quantum mechanics to provide us with alternative means of establishing security. Fortunately, the practical implementation of quantum cryptography has advanced considerably over that of quantum computation. We are therefore unlikely to face a 'security gap'. Indeed, the first commercial quantum key distribution systems have recently appeared on the market [2]. Developments such as these increase our confidence in quantum cryptography and lead us to enquire, more broadly, about which tasks requiring secure communication could be implemented using quantum states.

It is known that for some tasks, such as bit commit-

ment, quantum mechanics cannot help [3]. However, for others, such as secret sharing, a number of novel quantum protocols have been developed [4]. In an  $(n, k)$  secret sharing scheme, a classical message is split among  $n$  parties. The key property of such a scheme is that no less than  $k$  of these parties can extract any information about the secret, while any  $k$  of them can extract the secret in its entirety.

In some situations, it is more desirable that the identity of the person who sent the message, rather than the message itself, be kept secret [5]. Examples include elections, anonymous ballots and referendums. Here each voter should feel able to cast their vote without the prospect of coercion or repercussion. Only collective features of the set of votes, such as the tally of 'yes' and 'no' votes, are calculated and made public.

In this paper, we describe novel quantum protocols for voting and a related task that we term surveying. Surveying is similar to voting in most respects. The main difference is that in surveying, the value of the vote cast is not restricted to a binary 'yes' or 'no' but may take any integer value. As such, surveying corresponds to collecting estimates of some numerical quantity, such as profit and loss values. The identities of the people who make each bid are kept private, although the sum of the bids is made public. We also analyze the security of these protocols under some simple attacks.

To set our work in context, we review in section II a selection of protocols currently employed in secure classical election schemes. We devote section III to the description of our protocols. The first of these is a simple quantum protocol for *comparative voting*. Here, we consider two parties voting on a question with a 'yes' or 'no' answer. The aim is not to determine the tally itself, but to determine whether or not both parties voted identically without knowing the value of each of the votes. We show

that this is possible by encoding the voting information in an entangled state.

Subsequently, we describe a protocol for *anonymous surveying*. It proves robust against certain kinds of attack. We discuss adaptations of the protocol for an *anonymous ballot* for binary-valued ballots and the relationship between the privacy of a vote and the ability for a voter to cheat by making multiple votes. We conclude in section IV with a discussion of our results.

## II. CLASSICAL VOTING PROTOCOLS

Various properties have emerged from the literature as being desirable attributes of classical secret ballot voting schemes. Amongst these is the concept of *resilience* which involves the properties of universal verifiability, privacy, and robustness [6]. A *universally verifiable* election scheme is a scheme deemed open to scrutiny by all interested parties. Compliance with this property ensures that ballots are carried out correctly and that subsequent tallies are fairly assessed. For a scheme satisfying the *privacy* property an honest participant is assured that their vote remains confidential, provided that the number of attackers does not grow too large. With the property of *robustness*, an election scheme has the capacity to recover from faults again, provided that the number of parties involved does not grow too large. Schemes satisfying these three properties are said to be *resilient*. Another desirable property of an election scheme, particularly as a counter to the risk of vote buying or coercion, is that it is *receipt-free*. Receipt-free election schemes ensure that voters cannot prove, to other parties, the particular vote cast within the scheme [7, 8]. Further ‘desirable properties’ are to be found in the literature, for example [9].

Voting protocols performed within a classical setting are in general grouped according to their use of homomorphisms, MIX nets and blind signatures.

*Homomorphic election schemes.* These [6, 10, 11, 12, 13, 14] involve the use of a homomorphic, probabilistic encryption scheme consisting of a plaintext space  $\mathcal{V}$ , a ciphertext space  $\mathcal{C}$  (each of which form group structures  $(\mathcal{V}, \circ)$  and  $(\mathcal{C}, \circ')$  under appropriate binary operations  $\circ$  and  $\circ'$ ) together with a family of homomorphic encryption schemes  $\{E_i\}_{i \in \mathbb{N}^+}$  such that  $E_i : \mathcal{V} \rightarrow \mathcal{C}$  by  $v \mapsto c = E_i(v)$ . The homomorphic property [13] may be defined as follows: let  $c_j = E_{i_j}(v_j)$  and  $c_k = E_{i_k}(v_k)$  for  $j, i_j, k, i_k \in \mathbb{N}^+$ ; then  $\exists i \in \mathbb{N}^+$  s.t.  $c_j \circ' c_k = E_i(v_j \circ v_k)$ . Homomorphic election schemes are important since they allow one to derive tallies without the need to decrypt individual votes. Such schemes lead to resilient election schemes [6, 13].

*MIX net schemes.* MIX nets were first introduced by Chaum [15], and have found applications in scenarios involving anonymity, elections and payments. A MIX net election scheme involves the use of ‘shuffle machine agents’ referred to as MIX servers, [16] which take as input a ciphertext vector (these could be for example,

encrypted votes)  $(c_1, c_2, \dots, c_n) \in \bigoplus_{i=1}^n \mathcal{C}_i$  submitted by for example ‘voters’,  $(v_1, \dots, v_n)$  and produces as output a permuted vector (in which the components are shuffled) of corresponding output (for example, decrypted votes) such that the link between the source for each ciphertext (‘encrypted vote’) and its resulting plaintext (‘vote’) remains hidden. The resilience properties of privacy, verifiability and robustness may be presented in terms of ‘*t*-privacy’, ‘*t*-verifiability’ and ‘*t*-robustness’, where it is understood that *t* refers to the number of malicious MIX servers that the scheme can withstand given at most  $n-2$  malicious sources. A scheme satisfying the above three *t*-properties is said to be *t*-resilient [17].

The development of classical MIX net schemes to achieve, in particular, privacy initially led to ciphertext whose size was proportional to the number of MIX servers involved in the scheme. This problem was resolved by Park, Itoh and Kurosawa [16], resulting in ciphertext whose length was independent of the number of MIX servers. Sako and Kilian [18], produced a general MIX net scheme satisfying verifiability but failing with regard to robustness. The first resilient MIX net scheme was produced by Ogata, Kurosawa, Sako and Takatani [17, 19].

*Blind signature schemes.* These were also introduced by Chaum [20], and have been developed with applications in anonymity, election and payment schemes. The basic concept involves obtaining a signature to authenticate a ‘message’, for example an encrypted vote, without the signer being able to observe the message (‘vote’) itself or its signature. Verification regarding the signature is however supported by such schemes whilst maintaining privacy regarding the actual plaintext. A signer is thus denied the ability to link a particular plaintext with its corresponding ‘blind’ signature [21]. Variations upon such schemes are to be found with for example ‘Fair Blind Signatures’ [22] in which the possibility of, for example, blackmail is discussed [23].

*Sender untraceability schemes.* These schemes allow information to be sent anonymously. For example, in Chaum’s Dining Cryptographers’ Problem [24] a group of diners wish to determine if either an external agency or one of the group is paying anonymously for the meal. The solution requires 1 bit of information to be broadcast anonymously using a communication channel available to all diners. The simplest situation occurs for three diners with only two possible scenarios: one diner is to pay the bill or no diners pay the bill. The diner who pays broadcasts the message 1 in the following way. Each diner shares a single binary-digit one-time pad with the other two. The broadcast is executed by each diner adding the two numbers on the one time pads he or she holds. If one of the diners is paying he or she adds 1 to the value of the sum. The results modulo 2 are announced publicly to all diners. The sum of the 3 broadcast messages modulo 2 is 1 only if the message 1 is sent by a paying diner otherwise it is 0. Thus a message is broadcast but the identity of a paying diner is untraceable.

The security of a classical scheme is deemed to be one of two varieties: computational or unconditional (also known as information-theoretic) security [25]. A scheme which can be broken in principle but requires more computing power than a realistic adversary can access in a given critical time is deemed computationally secure. Examples are schemes based on the integer factorization problem and the discrete logarithm problem. Such computationally secure schemes are under threat from quantum computing. On the other hand, a scheme which is secure even if an adversary has unlimited computing resources is said to be unconditionally secure. A one time pad encryption scheme is unconditionally secure. Homomorphic maps and mixed nets not based on the one time pad are computationally secure. Blind signatures can be applied in an unconditionally secure manner to authenticate a vote and sender untraceability provides anonymity with unconditional security. Chaum's secret ballot protocol [26], which uses blind signature and sender untraceability schemes, allows unconditionally secret voting. The sender untraceability component of the protocol requires one-time pads between all pairs of voters, that is  $N(N-1)/2$  one time pads are required for a ballot with  $N$  voters.

### III. QUANTUM PROTOCOLS FOR ANONYMOUS SURVEYING AND VOTING

In this paper we examine a number of quantum protocols for ballots [32, 33]. In light of the foregoing classical schemes, we desire the ballots to satisfy the following general rules:

- (R1) The vote of each voter should be kept secret from all other voters.
- (R2) The person (the tallyman) calculating the collective quantity should not be able to gain information about the voting of individual voters.
- (R3) The votes should be receipt-free. This is to say that it should be impossible for a voter to prove how they voted to a third party, even if they wanted to. This condition thwarts vote buying and ensures the uncoercibility of the voter.

An additional rule applies for the special case of a restricted ballot where the range of values of each vote is restricted:

- (R4) A voter may not make more than one vote, that is, the value of each vote should not count as more than one vote.

We call a ballot where the votes are restricted to being binary-valued a *binary-valued ballot*. A specific example is a simple referendum. We call a ballot that satisfies the first three rules but not the fourth an *anonymous survey*.

Additional (ancillary) people may be involved in the ballot, but they must not have access to any more information about the voting than the tallyman. There are a number of different kinds of ballots depending on the nature of the ballot question and the collective voting information required.

#### A. Comparative ballot

The first quantum voting protocol we shall describe is a simple comparative protocol which we call a *comparative ballot*. Consider two voters, Alice and Bob, voting on a question with a response of either 'yes' or 'no'. There is also a tallyman, whose principal aim is to determine whether or not they agree, i.e., whether or not they have cast the same vote.

We wish the result of this comparison task to be deterministic and always correct (i.e. unambiguous). It should be noted in this context that, if instead of classical information, we wish to unambiguously compare pure quantum states, then certain restrictions would apply. In particular, the possible states would have to be linearly independent [27].

Alice and Bob are assumed to be at spatially separated sites  $A$  and  $B$ . The protocol entails beginning with the *ballot state* representing one particle shared between the two sites  $A$  and  $B$ :

$$|C_0\rangle = \frac{1}{\sqrt{2}}(|1, 0\rangle + |0, 1\rangle). \quad (1)$$

Here,  $|n, m\rangle \equiv |n\rangle_A \otimes |m\rangle_B$  represents  $n$  particles (bosons) occupying a spatial mode at site  $A$  and  $m$  particles occupying an orthogonal spatial mode at site  $B$  in second quantization notation. A voter makes a 'yes' vote by applying the operator  $\exp(i\hat{N}\pi)$ , where  $\hat{N}$  is the voter's local particle number operator and  $\exp(i\hat{N}\pi)|n\rangle = \exp(in\pi)|n\rangle$ . A 'no' vote is cast by simply doing nothing, which formally amounts to applying the identity operator. If both voters make the same vote, then the ballot state is unchanged (up to a possible overall sign inversion.) If, on the other hand, their votes are different, then the ballot state is transformed into

$$|C_1\rangle = \pm \frac{1}{\sqrt{2}}(|1, 0\rangle - |0, 1\rangle), \quad (2)$$

where the sign  $\pm$  depends on who votes 'yes'. At all times, the voter at one site cannot determine the vote cast at the other site. This is because the reduced density operator representing the state of the particle at each site is always the maximally-mixed state  $(|0\rangle\langle 0| + |1\rangle\langle 1|)/2$ . The voting is kept strictly private to the respective voters.

The two-particle state is then transferred to the site of the tallyman who performs a measurement in the basis  $(|1, 0\rangle \pm |0, 1\rangle)/\sqrt{2}$ . The tallyman is able to discern whether the voters have made the same or opposite vote

even though he is unable to determine how each voter cast their vote. This situation is similar in some respects to the Deutsch-Jozsa algorithm for deciding the balanced or unbalanced nature of a binary function [28]. Also the single particle state in Eq. (1) is the same state used in the data hiding protocol of Verstraete and Cirac [29]. Whereas in Ref. [29] a third party stores a secret in the state shared by Alice and Bob, here it is Alice and Bob who store secrets in the shared state. Our protocol satisfies rules 1 and 2 of private ballots, namely each vote is known only to its corresponding voter, and the tallyman has access only to the collective (comparative) information. The potential for cheating is limited by the very nature of the comparative ballot; voters can only make a single vote. The application of an operator other than  $\exp(i\hat{N}\pi)$  is interpreted as indecision in the sense that the result of repeated identical ballots is stochastic.

## B. Anonymous survey

In the above protocol, the voting information was stored in locally inaccessible phase factors in a entangled state. This technique can be applied to other situations where we wish to maintain anonymity. One such scenario is as follows.

Let us suppose that the chief executive officer (CEO) of a firm wants to gauge the effect of a possible action; he surveys the opinion of his management team to find out what each member thinks the likely profit (or loss) will be. To avoid the dishonest responses due to rivalry, grovelling, fear of repercussions etc., the CEO wants the survey to be anonymous. The managers must report the estimated profit or loss for their particular department. The CEO is interested in the total for the whole company. An alternative, but essentially equivalent, situation is that the managers estimate the total profit or loss for the firm as a whole, and the CEO wants the average of the estimates, that is, the sum of the estimates divided by the number of managers. In both cases the sum of the estimates is made public and the individual amounts are private. We call the protocol for determining the sum while keeping the individual amounts secret an *anonymous survey*.

An anonymous survey should obey the rules R1-R3. We now describe a quantum protocol that satisfies these rules. We retain the general terminology of ‘voters’, ‘votes’ and the ‘tally’. The basic principle of the protocol involves a *two-mode* discrete phase state [30, 31] shared between the voters and the tallyman. A vote is made by translating the phase value of the phase state. Due to the shared nature of the state, the actual value of the phase is hidden from both the voters and the tallyman in a manner analogous to secret sharing [29].

We again use a system of identical particles in the second quantization formalism. We employ  $N$  particles, where  $N$  is equal to or larger than the number of voters.

The particles are prepared in the following *ballot state*:

$$|B_0\rangle = \frac{1}{\sqrt{N+1}} \sum_{n=0}^N |N-n, n\rangle, \quad (3)$$

where  $|n, m\rangle \equiv |n\rangle_T \otimes |m\rangle_V$  and  $|n\rangle_V$  ( $|n\rangle_T$ ) represents  $n$  particles localized in a spatial mode at site  $V$  (respectively  $T$ ). The sites  $V$  and  $T$  are assumed to be remote from each other. Voters have access only to  $V$  and not  $T$ , whereas the tallyman has access only to  $T$  and not  $V$ . Voter  $i$  makes a vote by applying the phase shifting operation  $\exp(i\hat{N}_V\delta_i)$  to the spatial mode at site  $V$ , where  $\hat{N}_V|n\rangle_V = n|n\rangle_V$  and  $\delta_i = \nu_i\pi/(N+1)$  for a vote corresponding to an amount  $\nu_i$ . For example, after the vote of the first voter the ballot state becomes:

$$|B_1\rangle = \frac{1}{\sqrt{N+1}} \sum_{n=0}^N \exp(in\delta_1) |N-n, n\rangle. \quad (4)$$

The second voter makes a vote in a similar manner with the phase shifting angle  $\delta_2$ . This voting process is repeated for all voters. The resulting ballot state after the  $m$ th voter is

$$|B_m\rangle = \frac{1}{\sqrt{N+1}} \sum_{n=0}^N \exp(in\Delta_m) |N-n, n\rangle, \quad (5)$$

where  $\Delta_m = \sum_{i=1}^m \delta_i$ . The net value of the accumulated votes is  $M_m = \sum_{i=1}^m \nu_i$  which can be deduced from the final phase angle using

$$\Delta_m = \frac{2\pi M_m}{N+1}. \quad (6)$$

Note that at any point in this operation the tallyman, who does not have access to the site  $V$ , can only see the mixed state

$$\text{Tr}_V(|B_m\rangle\langle B_m|) = \frac{1}{N+1} \sum_{n=0}^N (|n\rangle\langle n|)_T, \quad (7)$$

which is invariant under the phase shifting operation. Likewise, the voters, who do not have access to the site  $T$ , can only see the mixed state

$$\text{Tr}_T(|B_m\rangle\langle B_m|) = \frac{1}{N+1} \sum_{n=0}^N (|n\rangle\langle n|)_V. \quad (8)$$

The voting of individual voters is therefore secret from other voters and the tallyman.

At the end of the survey the particles at site  $V$  are translated to a mode at site  $T$  so that the ballot state is as in Eq. (5) but with  $|n, m\rangle \equiv |n\rangle_T \otimes |m\rangle_T$ . We imagine that the tallyman has access to both modes at site  $T$ . The states  $|N-n, n\rangle$  form an orthonormal basis for an  $N+1$  dimensional subspace. We define another orthonormal basis as follows [30]:

$$|T_n\rangle = \frac{1}{\sqrt{N+1}} \sum_{k=0}^N \exp(ink\theta) |N-k, k\rangle, \quad (9)$$

where  $\theta = 2\pi/(N+1)$  and

$$\langle T_n | T_m \rangle = \delta_{nm} . \quad (10)$$

The ballot states are all eigenstates of the *tally operator*:

$$\hat{T} = \sum_{n=0}^N n |T_n\rangle \langle T_n| . \quad (11)$$

To find the tally, the tallyman finds the expectation value of the tally operator which yields:

$$\langle B_m | \hat{T} | B_m \rangle = M_m . \quad (12)$$

The tallyman can access the tally only once he is in possession of all particles. The voting of individual voters is kept secret from both the tallyman and the voters while the particles are shared between the sites.

*Attack by colluding voters.* Two voters,  $A$  and  $B$ , can collude in the following manner to deduce information about other voters. First we write the ballot state as

$$|B_0\rangle = \frac{\sqrt{N+1}}{2\pi} \int_0^{2\pi} |\psi(\theta)\rangle |\phi(\theta)\rangle d\theta , \quad (13)$$

where the single-mode phase states [30] are given by

$$|\psi(\theta)\rangle = \frac{1}{\sqrt{N+1}} \sum_{n=0}^N e^{-in\theta} |N-n\rangle , \quad (14)$$

$$|\phi(\theta)\rangle = \frac{1}{\sqrt{N+1}} \sum_{n=0}^N e^{in\theta} |n\rangle . \quad (15)$$

Imagine that voter  $A$  locally measures the phase of the system at the voting site; this will project the system onto a state of the form  $|\psi(\theta')\rangle |\phi(\theta')\rangle$ , where  $\theta'$  represents the outcome of the measurement. The tally  $M$  of votes of subsequent voters then accumulates locally in the phase of the local system, resulting in the state  $|\psi(\theta')\rangle |\phi(\theta' + M\delta)\rangle$ . Subsequent measurement of the phase by voter  $B$  and comparison with the phase measured by  $A$  will then reveal the amount  $M$ .

*Detection of attack.* We note that the ballot state, in the absence of the attack, has a fixed number of particles  $N$ . In contrast the projection onto a phase state induces a distribution of particles, and so the attack alters the total particle number on average. Thus the attack can be detected by the tallyman making a measurement of the total particle number  $\hat{N}$  and checking if it differs from  $N$ . The probability of detecting the attack by this method is  $1 - P_N$  where  $P_N = 1/(N+1)$  is the probability of finding  $N$  particles in the state  $|\psi(\theta')\rangle |\phi(\theta')\rangle$ .

*Defence.* A defence against this colluding attack is to use a multiparty ballot state such as

$$|B'_0\rangle = \frac{1}{\sqrt{N+1}} \sum_{n=0}^N |K(N-n), n, n, \dots, n\rangle , \quad (16)$$

where  $|i, j, \dots, k\rangle \equiv |i\rangle_T \otimes |j\rangle_{V_1} \otimes \dots \otimes |k\rangle_{V_K}$  for  $K$  voting sites  $V_i$ ,  $i = 1, \dots, K$  where  $K$  is equal to or larger than the number of voters. Each voter  $i$  is assigned a unique voting site  $V_i$  for casting a vote as before, i.e. using the phase shifting operation  $\exp(i\hat{N}_{V_i}\delta_i)$  to the spatial mode at site  $V_i$ . The colluding attack is foiled because each voting site is used by a single voter. The final multipartite ballot state is

$$|B'_m\rangle = \frac{1}{\sqrt{N+1}} \sum_{n=0}^N \exp(in\Delta_m) |K(N-n), n, n, \dots, n\rangle \quad (17)$$

and the corresponding multipartite tally operator is given by

$$\hat{T}' = \sum_{n=0}^N n |T'_n\rangle \langle T'_n| , \quad (18)$$

where

$$|T'_n\rangle = \frac{1}{\sqrt{N+1}} \sum_{k=0}^N \exp(ink\theta) |K(N-k), k, k, \dots, k\rangle . \quad (19)$$

After all the particles are translated to the tallyman, the tallyman determines the value of the tally from the expectation  $\langle B'_m | \hat{T}' | B'_m \rangle = M_m$  in the same manner as before.

### C. Anonymous binary-valued ballot

A special case of an anonymous survey is an anonymous ballot for binary-valued votes which we call an *anonymous binary-valued ballot*. A simple referendum would be a specific example of this kind of ballot. Here, instead of votes being an arbitrary integer, each vote is of a binary nature, ‘yes’ or ‘no’, corresponding to an answer to a public question. The anonymous survey protocol above could be used for an anonymous binary-valued ballot provided the voters were honest and restricted their vote value accordingly. For example, voter  $k$  could choose a phase shift angle of  $\delta_i = 0$  for a ‘no’ vote and  $\delta_i = 2\pi/(N+1)$  for a ‘yes’ vote. The tally  $M_m$  in Eq. (6) then corresponds to the number of ‘yes’ votes (the number of ‘no’ votes being calculated from the number of participating voters less  $M_m$ ). There are special situations where it is in the voters’ interest to vote honestly, for instance, where the public ballot question is one of a personal nature (requiring anonymity) and where the voters want to know the true proportion of voting population sharing the same view. Of course, in general, the voters may be tempted to vote more than once and, for example, a voter may choose  $\delta_k = 4\pi/(N+1)$  to record two ‘yes’ votes. It is therefore important that rule R4 is enforced in anonymous binary-valued ballots.

The underlying reasons why the anonymous protocol does not satisfy R4 are rather simple and quite general.

Consider two parties Alice and Bob, and the entire initial ballot state  $|B_0\rangle$ . Let  $Y_A$  and  $Y_B$  be the unitary operators used by Alice and Bob respectively to register ‘yes’ votes. It is assumed that they would both vote ‘no’ by applying the identity operator. Any tensor product structure arising from, e.g., Alice and Bob registering their votes on different systems is taken to be implicit in these definitions. Let us now consider the implications of anonymity and define

$$\Omega = \|(Y_A - Y_B)|B_0\rangle\|, \quad (20)$$

where  $\|\psi\rangle\| \equiv \langle\psi|\psi\rangle$ . Anonymity requires that for either a ‘yes’ or ‘no’ vote, it should be impossible to determine who made this vote. It therefore requires that  $\Omega = 0$ .

Let us now suppose that one of the parties, say Alice, wishes to cheat. She wishes to vote ‘yes’ twice by making it appear as though both she and Bob have voted ‘yes’, where Bob is some other voter who has voted ‘no’ (and in a sufficiently large ballot that such a party exists is a fair assumption). Suppose that Alice votes after Bob. Then, for Alice’s cheating to go undetected, the states  $Y_B Y_A |B_0\rangle$  and  $Y_B^2 |B_0\rangle$  must be completely indistinguishable. That this is the case under conditions of anonymity can be seen from

$$\|(Y_B Y_A - Y_B^2)|B_0\rangle\| = \|Y_B(Y_A - Y_B)|B_0\rangle\| = \Omega, \quad (21)$$

where the last step follows from the unitary invariance of the norm. Under conditions of anonymity,  $\Omega = 0$  and so the two states are completely indistinguishable, concealing Alice’s actions.

We may also require that Alice can cheat undetected irrespective of the order in which she and Bob cast their votes. This will be the case if

$$[Y_A, Y_B]|B_0\rangle = 0. \quad (22)$$

This condition is automatically satisfied if Alice and Bob register their votes on different systems, or the same operators if they use a common system, as is the case in the protocol we have described.

It follows that to protect against this kind of cheating strategy, some of the properties of the protocol must be changed. The key one seems to be unitarity. It is therefore interesting to explore the possibility of maintaining anonymity yet preventing cheating if we drop unitarity and use irreversible operations to register votes. We will now see that doing so does allow for a certain degree of improvement. In particular, we will see how the use of irreversibility can limit the extent of one party’s cheating to a mere 0.5 votes, and only at the expense of reduced privacy, in contrast with the limitless extent to which they can cheat using unitary operations with impunity.

The possibility of cheating can be restricted by introducing an element of irreversibility into the voting procedure. One way of doing this would be to restrict the operation able to be performed by each voter to the appropriate values by directly restricting the macroscopic devices used to perform the voting operations. However,

since the restricted device is not in the total control of the voter (by necessity) it seems likely that evidence of the action taken by the voter could be traced in the local environment and so criterion R1 is not guaranteed to be satisfied. This is clearly a general problem with irreversible operations.

One way to restrict the votes without macroscopic means is to replace the initial ballot state Eq. (3) with

$$|B_0''\rangle = \frac{1}{\sqrt{N+1}} \sum_{n=0}^N |2(N-n), n, n\rangle, \quad (23)$$

where  $|i, j, k\rangle \equiv |i\rangle_T \otimes |j\rangle_{V_1} \otimes |k\rangle_{V_2}$  and  $V_1$  and  $V_2$  label two voting sites which are controlled by two ballot agents  $A_1$  and  $A_2$ , respectively. Each voter privately records their vote in a (separate) pair of qutrits (i.e. a pair of spin-1 systems) with the state  $(|0, -1\rangle + |-1, 0\rangle)/\sqrt{2}$  for a ‘no’ vote or the state  $(|0, 1\rangle + |1, 0\rangle)/\sqrt{2}$  for a ‘yes’ vote. Here the qutrit states  $|-1\rangle$ ,  $|0\rangle$  and  $|1\rangle$  correspond to eigenstates of the  $z$  component of spin. One qutrit is given to each of the ballot agents who locally apply the operation

$$\exp[i\hat{N}^{(1)}\delta(\frac{1}{4} + \frac{1}{2}\hat{\sigma}_z^{(1)})] \otimes \exp[i\hat{N}^{(2)}\delta(\frac{1}{4} + \frac{1}{2}\hat{\sigma}_z^{(2)})], \quad (24)$$

where  $\delta = 2\pi/(N+1)$ ,  $\sigma_z^{(i)}$  is the  $z$  component of spin for qutrit  $i$  at site  $V_i$ , and  $\hat{N}^{(i)}$  operates on the spatial mode in  $|B_0''\rangle$  at site  $V_i$ . This allows the votes to accumulate in the discrete phase angle as before and ensures that each voter casts a single vote.

*Attacks by ballot agents.* The 2 separated ballot agents cannot separately learn the nature of the vote with certainty. For example, one ballot agent may measure the  $z$  component of spin on the qutrit at his site. This would reveal the nature of the vote only *half* of the time.

*Defence: tamper evidence.* The attack by the ballot agents will result in the qutrit pair being in a product of eigenstates of the  $z$  component of spin. Thus to detect the attack, the qutrit system should be immediately returned to the voter following the action by the ballot agents, and be subjected to measurement in a basis which includes the states representing ‘yes’ and ‘no’ votes to determine if the state has been changed. The attack will be detected one half of the time. Any instances of changed states are made public, and hence attempted cheating by a ballot agent will be detected, on average. The qutrit system is therefore *tamper evident*, on average, in this sense.

Alternatively, the privacy of the vote can be increased by increasing the number of ballot agents and the number of qutrits used to store each vote. For example, in a 3-qutrit, 3-ballot agent scheme, the ballot state would be

$$|B_0'''\rangle = \frac{1}{\sqrt{N+1}} \sum_{n=0}^N |3(N-n), n, n, n\rangle. \quad (25)$$

The votes would be made by preparing the states  $(|0, 0, -1\rangle + |0, -1, 0\rangle + |-1, 0, 0\rangle)/\sqrt{3}$  for a ‘no’ vote or

the state  $(|0, 0, 1\rangle + |0, 1, 0\rangle + |1, 0, 0\rangle)/\sqrt{3}$  for a ‘yes’ vote, and each ballot agent  $A_i$  applies the operation

$$\exp[i\hat{N}^{(i)}\delta(\frac{1}{6} + \frac{1}{2}\hat{\sigma}_z^{(i)})] \quad (26)$$

to their local qutrit system and the spatial mode of  $|B_0'''\rangle$ . A measurement of the  $z$ -component of spin of one of the qutrits by a ballot agent will now reveal the value of the vote only *one third* of the time, making the vote more private.

*Attacks by voters.* A voter need not prepare the states corresponding to a ‘yes’ or ‘no’ vote. Indeed, he may try to maximize the value of his vote, for example, by preparing the qutrit pair in the *cheat state*  $|1, 1\rangle$ . The action of the operator in Eq. (24) applied by the two ballot agents then increases the phase angle of the ballot state by  $3\delta/2$ , that is, by 1.5 votes [34].

*Defence: tamper-evidence versus vote-value tradeoff.* The attack by the voter may increase the value of the vote, but this is at the expense of abandoning the tamper-evident nature of the qutrit system. A measurement of the  $z$  component of spin of one of the qutrits in the cheat state will reveal the value of the vote without altering the state; this allows a ballot agent to determine the vote without being detected. Hence, a voter may cheat by a half vote but only at the expense of losing the privacy of his vote.

#### IV. DISCUSSION

We have introduced quantum protocols for ensuring the anonymous voting in a number of different scenarios. Central to the protocols is the ballot state, which is an entangled state shared between at least two sites. The ballot state stores the tally of the votes which are registered using local operations. At all times the value of the vote tally stored in the ballot state is not available at any one site, but only in the collection of the sites. The ballot therefore represents a *distributed memory* and this property ensures the privacy of each vote and thus the anonymity of each voter. After all votes have been made, the vote tally can be determined by a collective measurement.

We identified 4 rules (R1-R4) which lead to desirable properties of anonymous ballots. The different kinds of ballot depend on the ballot question, the collective information required and the subset of rules. We described protocols for a comparative ballot, where the ‘yes’ or ‘no’ answers of two voters are compared, an anonymous survey, where the voters make anonymous votes of integer value, and an anonymous binary-valued ballot, where the ‘yes’ and ‘no’ answers to a ballot question are tallied

anonymously. We note that an anonymous binary-valued ballot is closely related to an election, and indeed, it corresponds to an election for the special case of two candidates. We are currently exploring other possibilities.

We have analyzed our protocols against a number of attacks. In particular, we found that for the anonymous binary-valued ballot the cheating by a voter is associated with reduced security. In one variant of the protocol, while the value of the vote of an honest voter is 1, a dishonest voter can make a vote of value equal to 1.5 and essentially cheat by 0.5 vote. However, this occurs at the cost of reduced privacy since the *tamper-evident* nature of the protocol, which allows the voter to detect an attack by a ballot agent, is only available if an honest vote is made. The various schemes are unconditionally secure *on average* in the sense that attacks can be detected with non-zero probability.

For comparison, we note that Chaum’s classical secret ballot protocol is also unconditionally secure [26]. The secrecy is protected through the use of one-time pads which are shared between all pairs of voters. In a ballot with  $N$  voters, this requires each voter to distribute  $N - 1$  one time pads with the other voters. Thus the computational complexity of the protocol from the perspective of a voter is of order  $N$ . In contrast, in our quantum voting scheme each voter needs to share a *single* multiparty entangled state with the tallyman. For example the tallyman could locally prepare a set of spatial modes in the ballot state and then teleport the states of the entangled modes to each corresponding voter. The computational complexity from the perspective of a voter is therefore of order unity, which is an  $N$ -fold reduction.

We also found a related property [34] for our anonymous binary-valued ballot protocol as follows: as the protocol is modified to increase the privacy of the vote, the restriction on the possible values of an individual vote weakens. This appears to be a general trade-off property and we are currently exploring it in more detail. Indeed our results represent an initial study of this topic and are not intended to be complete. We hope our results will stimulate further research into this area.

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