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Homotopy Manin theories: generalising third-way, Yang-Mills and integrable sigma models

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Abstract

Manin theories are a class of non-topological deformations of Chern-Simons theories that naturally realise the third-way mechanism and furthermore admit localisation despite not being supersymmetric in the usual sense. In this paper, we extend this construction to higher dimensions, thereby producing a large class of examples of third-way-type theories. Furthermore, the construction naturally yields Yang-Baxter integrable deformations of the principal chiral model as well as gravitational models various dimensions.

Keywords: AKSZ model, third-way theory, Manin pair, integrable sigma model

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1. Introduction and summary

The Alexandrov–Kontsevich–Schwarz–Zaboronsky (AKSZ) sigma model [1] (reviewed in [2–6]) provides a uniform construction of many Schwarz-type topological field theories in any dimension (such as Chern–Simons theory, BF model, topological Yang–Mills theory $F \wedge F$, Poisson sigma model, etc) and provides structural insights in terms of their gauge structure as a symplectic Lie n-algebroid. They appear in holography [7, 8] and in double field theory [9].

This article extends the construction by deforming the AKSZ sigma models using a Dirac structure (or Manin pair). This class of (non-topological) theories, which we call Manin–AKSZ sigma models, provides a uniform construction of such diverse theories as (nonsupersymmetric) Yang–Mills theory, the third-way theories (a subsector of the ABJM model in a Romans background) [10–13] (reviewed in [14]), the Manin theories [15], Yang–Baxter integrable deformations [16, 17] (reviewed in [18, 19]) of the principal chiral model, and more. In particular, this provides a way to construct theories that exhibit the third way mechanism [10–13] using L_{∞} -algebras and L_{∞} -algebroids. Furthermore, many of this class of theories admit an interpretation as a gravitational theory coupled to backgrounds [20, 21]. For prior approaches to deforming AKSZ models to generate non-topological theories see, for example, [22–28] and the references therein.

2. Geometric structures

We recall the relevant notions of differential graded geometry in terms of which the Batalin–Vilkovisky formalism is naturally formulated, and define the notions of *admissible subalgebras* and *admissible fibrations* that define the geometry of homotopy Manin theories.

2.1. Symplectic differential graded manifolds

AKSZ models are naturally associated to symplectic differential graded manifolds, which we now review, fixing our conventions. For more comprehensive reviews see [5, 29, 30]. Our (graded) vector spaces are over the real numbers unless otherwise specified. We use the Koszul sign convention throughout. For a grading indexed by $i \in \mathbb{Z}$, $V = \bigoplus_i V_i$, suspensions are such that $(V[i])_j = V_{i+j}$. The symbol \odot denotes graded symmetrisation.

Definition 1. An L_{∞} -algebra $(\mathfrak{g}, \{\mu_i\}_{i=1}^{\infty})$ is a graded vector space $\mathfrak{g} = \bigoplus_i \mathfrak{g}^i$ equipped with totally graded-antisymmetric multilinear maps

$$\mu_i \colon \bigwedge^i \mathfrak{g} \to \mathfrak{g}$$
 (1)

of degree 2 - i such that

$$\sum_{\substack{i+j=k\\\sigma\in\operatorname{Sym}(k)}} \frac{\left(-1\right)^{ij}\chi\left(\sigma\right)}{i!j!}\mu_{j+1}\left(\mu_{i}\left(x_{\sigma\left(1\right)},\ldots,x_{\sigma\left(i\right)}\right),x_{\sigma\left(i+1\right)},\ldots,x_{\sigma\left(k\right)}\right)=0,\tag{2}$$

where $\chi(\sigma)$ is the graded-antisymmetric Koszul sign for the permutation σ . A *cyclic structure* of degree k on an L_{∞} -algebra $\mathfrak g$ is a graded-symmetric nondegenerate bilinear pairing

$$\langle \, , \, \rangle \colon \mathfrak{g}^{\bullet} \otimes \mathfrak{g}^{k-\bullet} \to \mathbb{R}$$
 (3)

that satisfies the following identity:

$$\langle x_1, \mu_i(x_2, \dots, x_{i+1})$$

$$= (-1)^{i+i(|x_1|+|x_{i+1}|)+|x_{i+1}|(|x_1|+\dots+|x_i|)} \langle x_{i+1}, \mu_i(x_1, \dots, x_i) \rangle.$$
(4)

A *cyclic* L_{∞} -algebra is an L_{∞} -algebra equipped with a cyclic structure.

Note that, if \mathfrak{g} is an L_{∞} -algebra concentrated in nonnegative degrees, then $\mathfrak{g}[1]$ is a differential graded manifold whose body is a single point.

Definition 2. A Lie *n*-algebroid (X, Q) is a nonnegatively graded manifold X concentrated in degrees $\{-n, 1-n, \ldots, 0\}$, together with a homological vector field Q on X of degree +1.

Example 1. A Lie 0-algebroid is the same thing as a smooth manifold (and Q = 0 necessarily).

Example 2. A Lie 1-algebroid (X, Q) is the same thing as a Lie algebroid. Then X has the structure of a vector bundle E[1] woheadrightarrow |X|. With appropriate local coordinates (x^i, θ^a) , then

$$Q = \rho_a^i \theta^a \frac{\partial}{\partial x^i} - \frac{1}{2} f^a{}_{bc} \theta^b \theta^c \frac{\partial}{\partial \theta^a}, \tag{5}$$

such that $\rho \colon E \to TX$ defines the anchor map, and f defines the bracket.

Example 3. A Lie *n*-algebroid (X, Q) over a point is the same as an L_{∞} -algebra \mathfrak{g} concentrated in degrees $\{1 - n, \dots, 0\}$. Concretely, $X = \mathfrak{g}[1]$, such that

$$C^{\infty}(X) = \bigcirc \mathfrak{g}[1]^*, \tag{6}$$

and then $Q: \mathcal{C}^{\infty}(X) \to \mathcal{C}^{\infty}(X)$ is the Chevalley–Eilenberg differential. Given a basis t_a of \mathfrak{g} ,

$$Q = -f^a \frac{\partial}{\partial t^a} - f^a{}_b t^b \frac{\partial}{\partial t^a} - \frac{1}{2} f^a{}_{bc} t^b t^c \frac{\partial}{\partial t^a} - \cdots,$$
 (7)

and $f^a{}_{b_1b_2...b_k}$ defines the structure constants for $\mu_k \colon \mathfrak{g}^{\wedge k} \to \mathfrak{g}$.

Definition 3. A symplectic Lie *n*-algebroid consists of a Lie *n*-algebroid (X, Q) equipped with a nondegenerate closed two-form $\omega \in \Omega^2(X)$ of degree $n + 2^6$.

For example, a symplectic 0-algebroid is the same thing as a symplectic manifold. On a smooth manifold Y, the degree-shifted tangent bundle T[1]Y is a Lie (1-)algebroid, and a symplectic structure on it is the same thing as a Poisson structure; a Lie 1-algebroid on the one-point space \bullet is the same thing as a Lie algebra, and a symplectic structure on it is the same thing as an invariant nondegenerate metric. A symplectic two-algebroid is the same thing as a Courant algebroid. A symplectic n-algebroid on \bullet is the same as (the décalage n of) a cyclic n-algebra in degrees n-algebra n

The following proposition is standard.

Proposition 1. Given a symplectic n-algebroid (X,Q,ω) and a point $x \in |X|$ in the body |X| of X, then there exists a canonical cyclic L_{∞} -algebra structure on the tangent space $T_x[-1]X$, where the cyclic structure is given by (the décalage of) ω_x and the L_{∞} -algebra structure is given by the Taylor expansion of Q near x.

⁶ Differential forms on a graded manifold are bigraded by form degree and the inherent degree of the coordinates.

⁷ Here, décalage refers to constructing an $L_{\infty}[1]$ -algebra from an L_{∞} -algebra; see e.g. [31].

2.2. Admissible subalgebras

The appropriate gauge structures for Manin theories in arbitrary dimensions are L_{∞} -algebras equipped with an isotropic *admissible subalgebra*. The admissible subalgebra defines the gauge subalgebra that is left unbroken by the mass term. This notion reduces to that of a Manin pair for Lie algebras.

Definition 4. Let \mathfrak{d} be an L_{∞} -algebra with a cyclic pairing of degree d-3 of split signature. An *admissible subalgebra* of \mathfrak{d} is a homogeneous Lagrangian subspace $\mathfrak{g} \subset \mathfrak{d}$ that satisfies the following three conditions:

1. For any $1 \le j \le i$ and $a_1 + \cdots + a_j \le j - 2$, we have

$$\mu_i(\mathfrak{g}^{a_1},\ldots,\mathfrak{g}^{a_j},\mathfrak{d},\ldots,\mathfrak{d})\subset\mathfrak{g}.$$
 (8)

2. For any $0 \le j \le i-1$ and $a \ge 3-d$ and $b_1 + \cdots + b_j \le j-2$, we have

$$\mu_i\left(\mathfrak{g}^a,\mathfrak{g}^{b_1},\ldots,\mathfrak{g}^{b_j},\mathfrak{d},\ldots,\mathfrak{d}\right)=0. \tag{9}$$

3. For any $a \ge 3 - d$, $a + b_1 + \cdots + b_{i-1} \ge 2 + i - d$, we have

$$\mu_i\left(\mathfrak{g}^a,\mathfrak{g}^{b_1},\ldots,\mathfrak{g}^{b_{i-1}}\right)\subset\mathfrak{g}.$$
 (10)

Example 4. In a Lie algebra \mathfrak{g} (regarded as an L_{∞} -algebra concentrated in degree zero), a linear subspace $\mathfrak{h} \subset \mathfrak{g}$ is an admissible subalgebra if and only if it is a Lie subalgebra.

Example 5. Given an vector space V equipped with a split-signature inner product $\langle -, - \rangle$, then $\mathfrak{d} := V[-1]$ may be regarded as a L_{∞} -algebra with $\mu_i = 0$ for all i and a cyclic structure of degree -2 = 1 - 3. Then an admissible subalgebra is the same as (the degree shift of) a Lagrangian subalgebra $L[-1] \subset V[-1]$.

Given a manifold Σ and an L_{∞} -algebra \mathfrak{d} the tensor product $\Omega(\Sigma) \otimes \mathfrak{d}$ carries the structure of an L_{∞} -algebra⁸, with products given by

$$\mu_i^{\Omega(\Sigma)\otimes\mathfrak{d}}\left(\alpha_1\otimes x_1,\ldots,\alpha_i\otimes x_i\right):=\pm\left(\alpha_1\wedge\cdots\wedge\alpha_i\right)\otimes\mu_i^{\mathfrak{d}}\left(x_1,\ldots,x_i\right)+\delta_{i1}\mathsf{d}\alpha_1\otimes x_i\tag{11}$$

for every homogeneous $\alpha_1,\ldots,\alpha_i\in\Omega(\Sigma)$ and $x_1,\ldots,x_i\in\mathfrak{d}$, where \pm is the Koszul sign corresponding to transpositions of α_1,\ldots,α_i and x_1,\ldots,x_i . Furthermore, it is cyclic if \mathfrak{d} is cyclic. This is, however, too large for homotopy Manin theories, where we wish to kill half of the gauge symmetry (into \mathfrak{g} -valued ghosts rather than \mathfrak{d} -valued ghosts for an admissible subalgebra $\mathfrak{g}\subset\mathfrak{d}$)). This breaking of the gauge symmetry is what will ultimately yield propagating degrees of freedom, generalising the construction introduced in [15]. An appropriately smaller L_∞ -algebra is provided by the following theorem.

Theorem 1. Let Σ be a d-dimensional compact oriented manifold, and $\mathfrak d$ be a cyclic L_∞ -algebra concentrated in degrees $\{2-d,\ldots,0,1\}$, such that one can construct the L_∞ -algebra $\Omega(\Sigma)\otimes\mathfrak d$. Let $\mathfrak g$ be an admissible subalgebra of $\mathfrak d$. Then the following holds.

1. the homogeneous subspace $\tilde{\Omega}(\Sigma; \mathfrak{d}, \mathfrak{g}) \subset \Omega(\Sigma) \otimes \mathfrak{d}$ given by

$$\tilde{\Omega}^{i}(\Sigma; \mathfrak{d}, \mathfrak{g}) := \begin{cases}
\bigoplus_{p+q=i} \Omega^{p}(\Sigma; \mathfrak{g}^{q}) & i \leq 0 \\
\bigoplus_{p+q=i} \Omega^{p}(\Sigma; \mathfrak{d}^{q}) & i \geq 1
\end{cases}$$
(12)

⁸ Since the de Rham algebra $\Omega(\Sigma)$ carries the structure of a graded-commutative associative algebra.

 \Box

is an L_{∞} -subalgebra of $\Omega(\Sigma) \otimes \mathfrak{d}$.

2. The homogeneous subspace $\tilde{\Omega}^i(\Sigma;\mathfrak{g}) \subset \tilde{\Omega}(\Sigma;\mathfrak{d},\mathfrak{g})$ given by

$$\check{\Omega}^{i}(\Sigma; \mathfrak{g}) := \begin{cases}
0 & i \leq 2 \\
\bigoplus_{p+q=i} \Omega^{p}(M; \mathfrak{g}^{q}) & i \geq 3
\end{cases}$$
(13)

is an L_{∞} -ideal of $\tilde{\Omega}(\Sigma; \mathfrak{d}, \mathfrak{g})$.

Thus, the subquotient

$$\hat{\Omega}(\Sigma; \mathfrak{d}, \mathfrak{g}) := \tilde{\Omega}(\Sigma; \mathfrak{d}, \mathfrak{g}) / \tilde{\Omega}(\Sigma; \mathfrak{g}) \tag{14}$$

exists as an L_{∞} -algebra.

Proof of 1. We must show that $\tilde{\Omega}(\Sigma; \mathfrak{d}, \mathfrak{g}) \subset \Omega(\Sigma) \otimes \mathfrak{d}$ is closed under $\mu_i^{\Omega(\Sigma) \otimes \mathfrak{d}}$ (which we simply write as μ_i below).

- Closure under μ_1 : we must check that, for $\alpha \otimes x$ with $\alpha \in \Omega^p(\Sigma)$ and $x \in \mathfrak{g}^q$ and p+q<1, that $d\alpha \otimes x + (-1)^p \alpha \otimes \mu_1^{\mathfrak{d}}(x) \in \tilde{\Omega}(\Sigma; \mathfrak{d}, \mathfrak{g})$. Now, $d\alpha \otimes x \in \Omega^{p+1}(\Sigma; \mathfrak{g}^q) \subset \tilde{\Omega}^{p+q+1}(\Sigma; \mathfrak{d}, \mathfrak{g})$. As for the other term, the argument in the case μ_i for general i applies verbatim.
- Given the above, it suffices to show that

$$\mu_{i}\left(\Omega^{p_{1}}\left(\Sigma;\mathfrak{g}_{-a_{1}}\right),\ldots,\Omega^{p_{j}}\left(\Sigma;\mathfrak{g}_{-a_{j}}\right),\Omega^{q_{1}}\left(\Sigma;\mathfrak{d}_{-b_{1}}\right),\ldots,\Omega^{q_{i-j}}\left(\Sigma;\mathfrak{d}_{-b_{i-j}}\right)\right)\in\Omega\left(\Sigma\right)\otimes\mathfrak{g}$$
(15)

whenever $p_1 - a_1, ..., p_i - a_i \le 0$ and $q_1 - b_1, ..., q_{i-i} - b_{i-i} \ge 1$ and

$$(2-i) + (p_1 - a_1) + \dots + (p_j - a_j) + (q_1 - b_1) + \dots + (q_{i-j} - b_{i-j}) \le 0.$$

$$(16)$$

It thus follows that we can without loss of generality set the form degrees to their minimum values, that is, to ensure

$$\mu_{i}\left(\Omega^{0}\left(\Sigma;\mathfrak{g}_{-a_{1}}\right)\otimes\ldots\otimes\Omega^{0}\left(\Sigma;\mathfrak{g}_{-a_{j}}\right)\otimes\Omega^{1+b_{1}}\left(\Sigma;\mathfrak{d}_{-b_{1}}\right)\otimes\cdots\right.\\\left.\otimes\Omega^{1+b_{i-j}}\left(\Sigma;\mathfrak{d}_{-b_{i-j}}\right)\right)\in\Omega\left(\Sigma\right)\otimes\mathfrak{g}$$
(17)

whenever

$$(2-i) - a_1 - \dots - a_i + (i-j) \le 0. \tag{18}$$

But this follows from (8).

Proof of 2. We must check the ideal condition for $\mu_i^{\Omega(\Sigma)\otimes \mathfrak{d}}$, that is, to show that the value of $\mu_i^{\Omega(\Sigma)\otimes \mathfrak{d}}$ lies in $\check{\Omega}(\Sigma;\mathfrak{g})$ whenever at least one of its argument belongs to $\check{\Omega}(\Sigma;\mathfrak{g})$ and the rest (if any) belong to $\tilde{\Omega}(\Sigma;\mathfrak{d},\mathfrak{g})$. As before, we simply write μ_i for $\mu_i^{\Omega(\Sigma)\otimes \mathfrak{d}}$.

The operator $\mu_1(\alpha \otimes x) = d\alpha \otimes x + (-1)^{|\alpha|} \alpha \otimes \mu_1^{\mathfrak{d}}(x)$ contains two terms, among which the first term always increases form degree and hence can pose no problem. Hence it suffices to ensure that

$$\mu_{i}\left(\Omega^{p}\left(\Sigma;\mathfrak{g}^{-a}\right),\Omega^{q_{1}}\left(\Sigma;\mathfrak{g}^{-b_{1}}\right),\ldots,\Omega^{q_{j}}\left(\Sigma;\mathfrak{g}^{-b_{j}}\right),\ldots,\Omega^{r_{1}}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{q_{j}}\left(\Sigma;\mathfrak{g}^{-b_{j}}\right),\ldots,\Omega^{r_{1}}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega$$

whenever $p-a \geqslant 3$ and $r_1-c_1,\ldots,r_{i-j-1}-c_{i-j-1}\geqslant 1$. There are two ways in which (19) could fail: (a) the total degree might dip to < 3 so that we fall out of $\check{\Omega}(\Sigma;\mathfrak{d},\mathfrak{g})$; (b) the $\mu_i^{\mathfrak{d}}$ might make me fall out of $\check{\Omega}(\Sigma;\mathfrak{d},\mathfrak{g})$ in that we end up in $\check{\Omega}(\Sigma;\mathfrak{d},\mathfrak{g})\setminus\Omega(\Sigma;\mathfrak{g})$. To avoid (a), it suffices without loss of generality to consider the case when all form degrees are minimised, that is, to ensure

$$\mu_{i}\left(\Omega^{3-a}\left(\Sigma;\mathfrak{g}^{-a}\right),\Omega^{0}\left(\Sigma;\mathfrak{g}^{-b_{1}}\right),\ldots,\Omega^{0}\left(\Sigma;\mathfrak{g}^{-b_{j}}\right),\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{c_{1}+1}\left(\Sigma;$$

whenever

$$(2-i)+3-b_1-\cdots-b_j+(i-j-1) \le 2. (21)$$

But this follows from (9). To avoid (b), we need to ensure that

$$\mu_{i}\left(\Omega^{p}\left(\Sigma;\mathfrak{g}^{-a}\right),\Omega^{q_{1}}\left(\Sigma;\mathfrak{g}^{-b_{1}}\right),\ldots,\Omega^{q_{j}}\left(\Sigma;\mathfrak{g}^{-b_{j}}\right),\ldots,\Omega^{r_{1}}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{r_{1}}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{r_{1}}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{r_{2}}\left(\Sigma;\mathfrak{d}^{-c_{1}}\right),\ldots,\Omega^{r_{2}}\left(\Sigma;\mathfrak{d}^{-c_{2}}\right),\ldots,\Omega$$

whenever $p - a \ge 3$ and $r_1 - c_1, \dots, r_{i-i-1} - c_{i-i-1} \ge 1$ and

$$(2-i)+(p-a)+(q_1-b_1)+\cdots+(q_i-b_i)+(r_1-c_1)+\cdots+(r_{i-j-1}-c_{i-j-1})\geqslant 3$$
 (23)

and

$$p + q_1 + \dots + q_i + r_1 + \dots + r_{i-i-1} \le d.$$
 (24)

That is, given $(-a, -b_1, \ldots, -b_j, -c_1, \ldots, -c_{i-j-1})$, if we can choose (p, q, r) so that the above inequality is satisfied, then the corresponding $\mu_i^{\mathfrak{d}}$ has to take values in \mathfrak{g} .

$$1 + i + a + (b_1 - q_1) + \dots + (b_j - q_j) + (c_1 - r_1) + \dots + (c_{i-j-1} - r_{i-j-1})$$

$$\leq p$$

$$\leq d - q_1 - \dots - q_j - r_1 - \dots - r_{i-j-1}.$$
(25)

Such a p exists iff

$$a + b_1 + \dots + b_i + c_1 + \dots + c_{i-i-1} \le d - 1 - i.$$
 (26)

But now we see that the condition (10) is the condition that we need.

Definition 5. Given a multiset of nonnegative integers *S*, property (A) holds iff there is at most one element of *S* is positive:

$$(A) \iff \#\{s \in S \mid |s| > 0\} \leqslant 1. \tag{27}$$

(Here # denotes the cardinality of a multiset.) Property (B) holds iff all but two elements of S are zero, and the two remaining elements are equal:

$$(B) \iff \exists p \in \mathbb{N} \colon S = \{0, \dots, 0\} \sqcup \{p, p\}. \tag{28}$$

(Properties (A) and (B) hold simultaneously iff S only contains zeros.)

Definition 6. A *Hodge structure* on an admissible subalgebra $\mathfrak g$ of a cyclic L_∞ -algebra $\mathfrak d$ (where $\mathfrak d$ carries cyclic structure of degree 3-d) consists of nondegenerate symmetric (*not* graded-symmetric) bilinear pairings

$$\varkappa^{(i)} \colon \left(\mathfrak{d}^i/\mathfrak{g}^i\right) \otimes \left(\mathfrak{d}^i/\mathfrak{g}^i\right) \to \mathbb{R} \tag{29}$$

for each degree i, which we can regard (using the isomorphism⁹ $\mathfrak{g}^{d-3-i} \cong (\mathfrak{d}^i/\mathfrak{g}^i)^*$) as linear maps

$$M^{(i)}: \mathfrak{d}^i \to \mathfrak{d}^{d-3-i} \tag{30}$$

with

$$\operatorname{im} M^{(d-3-i)} = \mathfrak{g}^{i} = \ker M^{(i)} \qquad (i \leqslant 0), \tag{31}$$

and that is cyclic in that

$$\langle Mx, y \rangle = \langle x, My \rangle \tag{32}$$

for any $x, y \in \mathfrak{d}$, such that given $a_1, \ldots, a_i \in \{2 - d, \ldots, 1\}$ and $p_1, \ldots, p_i \in \{0, \ldots, d\}$,

• if neither (A) nor (B) hold for the multiset $\{p_1, \dots, p_i\}$, then

$$X^{a_1,p_1;\dots;a_i,p_i} \in V$$
 $Y_k^{a_1,p_1;\dots;a_i,p_i} \in V$ (33)

for all $k \in \{1, ..., i\}$;

• if only (A) holds, then

$$X^{a_1,p_1;\dots;a_i,p_i} + Y_k^{a_1,p_1;\dots;a_i,p_i} \in V$$
(34)

for all $k \in \{1, ..., i\}$ and $p_k \geqslant 1$;

• if only (B) holds, then

$$Y_k^{a_1,p_1;\dots;a_i,p_i} + (-1)^{p_k(d-p_k)} Y_l^{a_1,p_1;\dots;a_i,p_i} \in V$$
(35)

for all $k, l \in \{1, ..., i\}$ with $p_k = p_l \geqslant 1$;

• if both (A) and (B) hold (i.e. $p_1 = \cdots = p_i = 0$), then

$$X^{a_1,p_1;\dots;a_i,p_i} + \sum_{k=1}^{i} Y_k^{a_1,p_1;\dots;a_i,p_i} \in V.$$
(36)

In the above,

 $X^{a_1,p_1;\cdots;a_i,p_i}$

$$:= \begin{cases} M(\mu_i(\tilde{\mathfrak{g}}^{a_1}, \dots, \tilde{\mathfrak{g}}^{a_i})) & \text{if } p_1 + \dots + p_i \leqslant d \text{ and } a_1 + p_1 + \dots + a_i + p_i = i - 1 \\ 0 & \text{otherwise} \end{cases}$$
 (37)

and

$$Y_k^{a_1,p_1;\cdots;a_i,p_i}$$

$$\begin{cases} \mu_k(\tilde{\mathfrak{g}}^{a_1} & M(\tilde{\mathfrak{g}}^{a_k}) & \tilde{\mathfrak{g}}^{a_i}) & \text{if } p_1+\ldots+p_k \leq 2p_k \end{cases}$$

$$:= \begin{cases} \mu_i(\tilde{\mathfrak{g}}^{a_1}, \dots, M(\tilde{\mathfrak{g}}^{a_k}) \dots, \tilde{\mathfrak{g}}^{a_i}) & \text{if } p_1 + \dots + p_i \leqslant 2p_k \text{ and } a_k + p_k = 1\\ 0 & \text{otherwise} \end{cases}$$
(38)

 $^{^9}$ This isomorphism exists because $\mathfrak g$ is a homogeneous Lagrangian subspace with respect to a degree d-3 pairing.

where *M* is applied to the *k*th argument $(k \in \{1, ..., i\})$, and in which

$$\tilde{\mathfrak{g}}^{a_k} := \begin{cases} \mathfrak{g}^{a_k} & a_k + p_k \leqslant 0\\ \mathfrak{d}^{a_k} & a_k + p_k \geqslant 1 \end{cases}$$
(39)

and

$$V = \begin{cases} \mathfrak{g} & \text{if } a_1 + p_1 + \dots + a_i + p_i \geqslant i \\ 0 & \text{otherwise.} \end{cases}$$
 (40)

Example 6. Let \mathfrak{d} be a cyclic Lie algebra with a Lagrangian subalgebra $\mathfrak{g} \subset \mathfrak{d}$. Then a Hodge structure on $(\mathfrak{d}, \mathfrak{g})$ is a linear map $M \colon \mathfrak{d} \to \mathfrak{d}$ with im $M = \mathfrak{g} = \ker M$ such that

$$\langle Mx, y \rangle = \langle x, My \rangle \tag{41}$$

for any $x, y \in \mathfrak{d}$ and

$$M[x,y] = [x,My] \tag{42}$$

for any $x \in \mathfrak{g}$ and $y \in \mathfrak{d}$.

Example 7. Let \mathfrak{g} be an L_{∞} -algebra with cyclic pairing of degree 3-n. Then

$$\mathfrak{d} = \mathfrak{g} \oplus \mathfrak{g}^* \tag{43}$$

forms a Manin pair. A Hodge structure consists of suitable (anti-)symmetric pairings on each of \mathfrak{g}_i .

Theorem 2. Let Σ be a d-dimensional compact oriented Riemannian manifold, and $\mathfrak d$ be a cyclic L_∞ -algebra concentrated in degrees $\{2-d,\ldots,-1,1\}$ with an admissible subalgebra $\mathfrak g$. Let M be a Hodge structure on $(\mathfrak d,\mathfrak g)$. Then the L_∞ -algebra structure $\mu_i^{\hat{\Omega}^i(\Sigma;\mathfrak d,\mathfrak g)}$ on $\hat{\Omega}(\Sigma;\mathfrak d,\mathfrak g)$ admits a one-parameter deformation

$$\mu_1^M := \mu_1^{\hat{\Omega}(\Sigma;\mathfrak{d},\mathfrak{g})} + t\nu \qquad \qquad \mu_i^M := \mu_i^{\hat{\Omega}(\Sigma;\mathfrak{d},\mathfrak{g})} \qquad \forall i \geqslant 2 \tag{44}$$

where t is an arbitrary real number and

$$\nu(\alpha \otimes x) := \begin{cases} \star \alpha \otimes M(x) & \text{if } |x| + |\alpha| = 1\\ 0 & \text{otherwise} \end{cases}$$
 (45)

for any $\alpha \in \Omega(\Sigma)$ and $x \in \mathfrak{d}$, where \star is the Hodge star on $\Omega(\Sigma)$. Furthermore, this deformation is cyclic¹⁰.

Proof. We first show that the L_{∞} -algebra homotopy Jacobi identities hold for μ_i^M . It is convenient to decompose the L_{∞} -algebra homotopy Jacobi identities according to the power of the formal parameter t, so that we have the $\mathcal{O}(t^0)$, $\mathcal{O}(t)$, and $\mathcal{O}(t^2)$ components, which must each vanish separately.

- The $\mathcal{O}(t^0)$ component of the homotopy Jacobi identities for μ_i^M is the original homotopy Jacobi identities of $\tilde{\Omega}^i(\Sigma;\mathfrak{d},\mathfrak{g})$, so there is nothing to check.
- The $\mathcal{O}(t^2)$ component of the homotopy Jacobi identities for μ_i^M vanishes since $\nu \circ \nu = 0$ for degree reasons: ν is only nonzero on elements of degree one.

¹⁰ It is possible to generalise to topological deformations that do not require the Hodge star [21]. We leave this analysis for future work.

• The $\mathcal{O}(t)$ component of the homotopy Jacobi identities for μ_i^M is

$$\nu\left(\mu_i^{\hat{\Omega}^i(\Sigma;\mathfrak{d},\mathfrak{g})}(x_1,\ldots,x_i)\right) + \sum_{i=1}^i \pm \mu_i^{\hat{\Omega}^i(\Sigma;\mathfrak{d},\mathfrak{g})}(x_1,\ldots,\nu(x_j),\ldots,x_i) = 0.$$
 (46)

The operator $\mu_i^{\hat{\Omega}(\Sigma;\mathfrak{d},\mathfrak{g})}$ has two kinds of terms: one (only present on $\mu_1^{\hat{\Omega}(\Sigma;\mathfrak{d},\mathfrak{g})}$) involving the exterior derivative of forms, and the other involving $\mu_i^{\mathfrak{d}}$ and wedge products of differential forms

Let us first check the exterior derivative term on $\mu_1^{\hat{\Omega}(\Sigma;\mathfrak{d},\mathfrak{g})}$. Given $\alpha \in \Omega^{\bullet}(X)$ and $x \in \mathfrak{d}$, the L_{∞} -algebra identity is

$$[|\alpha| + |x| = 0] \star d\alpha \otimes M(x) + [|\alpha| + |x| = 1] d \star \alpha \otimes M(x) \in V, \tag{47}$$

where $[\cdots]$ is the Iverson bracket [32] (1 if the enclosed statement is true, 0 otherwise). When $|\alpha| + |x| = 0$, we need $\alpha \in \mathfrak{g}$, and the term vanishes since $M(\mathfrak{g}) = 0$. When $|\alpha| + |x| = 1$, then $M(x) d \star \alpha$ carries degree 3, and since $M(x) \in \mathfrak{g}$, the result belongs to V. (As a special case: if |x| = 1, then the first Iverson bracket can never be true; the second Iverson bracket is nonzero only if |x| = 0, but then the second term vanishes for form-degree reasons.)

Let us consider the other terms in $\mu_i^{\hat{\Omega}(\Sigma;\mathfrak{d},\mathfrak{g})}$, that is, those which are $\mu_i^{\mathfrak{d}}$ with the form legs wedged together. In (46), applied to i arguments of form degrees p_1,\ldots,p_i and internal degrees a_1,\ldots,a_i , one sees that since Hodge stars do not distribute across wedge products, the terms cannot cancel each other unless condition (A) or condition (B) holds. When neither hold, then each term must vanish individually, corresponding to (33). When condition (A) holds (all but one are 0-forms), we have the identity

$$\star (\alpha_0 \wedge \alpha_1 \wedge \dots \wedge \alpha_i) = \alpha_0 \wedge \alpha_1 \wedge \dots (\star \alpha_k) \wedge \dots \wedge \alpha_i \tag{48}$$

where all the α s are zero-forms except for α_k , so that (34) suffices. When condition (B) holds (all but two are 0-forms, and the two have the same form degree), we have the identity

$$\alpha_0 \wedge \dots \wedge (\star \alpha_k) \wedge \dots \wedge \alpha_i = (-1)^{|\alpha_k|(d-|\alpha_k|)} \alpha_0 \wedge \dots \wedge (\star \alpha_l) \wedge \dots \wedge \alpha_i \quad (49)$$

where α_k and α_l are the two forms with positive degree, and then (35) suffices. When all forms are 0-forms, then we can relax the condition to (36).

Finally, cyclicity of μ_1^M follows from (32).

2.3. Admissible fibrations on symplectic dg-manifolds

We now formulate a notion analogous to Manin pairs in a Lie algebra, which is necessary to consider homotopy Manin theories with nonlinear target spaces.

Definition 7. An *admissible fibration* consists of a graded vector bundle p: X woheadrightarrow Y on a graded manifold Y together with a homological vector field Q and a symplectic form ω on X and an Ehresmann connection

$$TX = V_p \oplus H \tag{50}$$

(where V_p is the vertical bundle) such that:

- ω is bilinear on each fibre of p
- Q is a finite sum of homogeneous components with respect to the linear structure on the fibres of p,

• for any every $x \in X$, the fibre

$$H_x \subset T_x X$$
 (51)

defines an isotropic subspace of the cyclic L_{∞} -algebra T_xX that is also an admissible subalgebra.

Note that this notion is similar to, but differs from, the notions of Dirac structures in [33], Λ -structures in [34], or homotopy Manin pairs defined in [35, Def. 34]. Our notion is adapted to the current context of homotopy Manin theories.

Definition 8. A *Hodge structure* on an admissible fibration $(p: X \to Y, H)$ is a family of Hodge structures defined for the family of admissible subalgebras $H_x \subset T_x X$ for each $x \in X$ that is smooth with respect to X and constant along the fibre directions.

3. Homotopy Manin sigma models

Using the algebraic and geometric structures from the previous section, we now deform the topological AKSZ sigma models to construct non-topological homotopy Manin sigma models.

Let us recall the construction of an AKSZ sigma model. Given a spacetime (or world-volume) Σ and a symplectic *n*-algebroid (X, Q, ω) , then the space

$$\mathcal{M} := \mathcal{C}^{\infty} \left(T[1] \Sigma, X \right) \tag{52}$$

of graded-smooth maps carries canonically the structure of a symplectic (Fréchet) dg-manifold $(\mathcal{M}, Q_{\mathcal{M}}, \omega_{\mathcal{M}})$ with a symplectic form $\omega_{\mathcal{M}}$ of degree -1, whose coordinates are concentrated in degrees $-n, \ldots, 0$. This may be regarded as a BV-extended configuration space satisfying the classical master equation.

Let M be a Hodge structure on an admissible fibration X woheadrightarrow Y. Let us deform the differential $Q_{\mathcal{M}}$ by

$$Q_{\mathcal{M}}' = Q_{\mathcal{M}} + \star M t_a \frac{\partial}{\partial t^a},\tag{53}$$

where t_a are the coordinates of degree 0 (the fields) and t^a are the corresponding coordinates of degree -1 (the antifields) with a DeWitt index a. This vector field is not nilpotent on \mathcal{M} . However, let $\tilde{\mathcal{M}}$ be the subspace of \mathcal{M} consisting only of the following coordinates:

- any coordinates of degrees 0 or 1
- any coordinates of degrees other than 0 or 1 that are constant along the fibres of the admissible fibration.

Then $Q'_{\mathcal{M}}$ restricted to $\tilde{\mathcal{M}}$ is nilpotent, so that $(\tilde{\mathcal{M}}, Q'_{\mathcal{M}}, \omega|_{\tilde{\mathcal{M}}})$ forms a symplectic dg-manifold. The *homotopy Manin theory* associated to the data (X, L, M) is the classical field theory whose BV formulation is given by the above symplectic dg-manifold.

Example 8. Consider the case where the body of $X = \mathfrak{d}[1]$ is a single point. Then we are simply dealing with a cyclic L_{∞} -algebra \mathfrak{d} and an admissible subalgebra $\mathfrak{g} \subset \mathfrak{d}$. Then the L_{∞} -algebra associated to the homotopy Manin theory has the underlying graded vector space

$$\mathfrak{G} = \bigoplus_{p,q} \Omega^p(\Sigma) \otimes \mathfrak{d}_p^q \subset \Omega(\Sigma) \otimes \mathfrak{d}, \tag{54}$$

where

$$\mathfrak{d}_{p}^{q} := \begin{cases} \mathfrak{d}^{q}/\mathfrak{g}^{q} & 2 (55)$$

The L_{∞} -algebra structure μ_i on $\mathfrak G$ is given by restriction of the L_{∞} -algebra structure $\mu_i^{\Omega^{ullet}(\Sigma)\otimes\mathfrak d}$ on $\Omega^{ullet}(\Sigma)\otimes\mathfrak d$ to the above subspace, except that μ_1 has an extra term:

$$\mu_{i} = \mu_{i}^{\Omega^{\bullet}(\Sigma) \otimes \mathfrak{d}}|_{\mathfrak{G}} \qquad (i > 1)$$

$$\mu_{1}(x) = \begin{cases} \mu_{1}^{\Omega^{\bullet}(\Sigma) \otimes \mathfrak{d}}(x) + M \star x & |x| = 1\\ \mu_{1}^{\Omega^{\bullet}(\Sigma) \otimes \mathfrak{d}}(x) & |x| \neq 1. \end{cases}$$
(56)

3.1. Action of homotopy Manin models in local coordinates

Given that the homotopy Manin theory is given by a symplectic dg-manifold, it admits an action formulation. (As such, the class of homotopy Manin theories described here cannot suffer from the kind of failure of unitarity described in [36].)

We can write down the corresponding classical homotopy Maurer–Cartan (hMC) action for the (deformed) cyclic L_{∞} -algebra $\hat{\Omega}(\Sigma; \mathfrak{d}, \mathfrak{g}), \mu_i^M$:

$$S = \int_{\Sigma} \left\langle \mathbb{A}, \sum_{i} \frac{1}{(i+1)!} \mu_{i}^{M}(\mathbb{A}, \dots, \mathbb{A}) \right\rangle$$

$$= \int_{\Sigma} \left(\frac{1}{2} \langle \mathbb{A}, d\mathbb{A} \rangle + \frac{1}{(i+1)!} \left\langle \mathbb{A}, \sum_{i} \mu_{i}^{\mathfrak{d}}(\mathbb{A}, \dots, \mathbb{A}) \right\rangle + \frac{1}{2} \langle \mathbb{A}, \star M \mathbb{A} \rangle \right)$$
(57)

restricted to the space of ordinary fields (rather than antifields, ghosts, or ghost antifields), which is given by $\mathbb{A} \in \bigoplus_i \Omega^{1+i}(\Sigma; \mathfrak{d}_{-i})$.

Picking a splitting for convenience, this is

$$\bigoplus_{i} \Omega^{1+i} \left(\Sigma; \mathfrak{g}_{-i} \right) \oplus \Omega^{1+i} \left(X; \left(\mathfrak{g}_{i} \right)^{*} \right). \tag{58}$$

Call the first component A (the dynamical field) and the second component \tilde{A} (the field made auxiliary by the mass term). Then the action is

$$\int_{\Sigma} hMC \left(A \oplus \tilde{A} \right) + \frac{1}{2} \langle \tilde{A} \wedge \star M\tilde{A} \rangle. \tag{59}$$

3.2. Energy positivity

We briefly examine the Hamiltonian formulation of an arbitrary homotopy Manin gauge theory in order to demonstrate that the Hamiltonian (*sans* constraints) is bounded from below. In other words these gauge theories have positive energy.

The calculation is essentially the same as in [15]. First, we perturbatively expand the symplectic L_{∞} -algebroid into a cyclic L_{∞} -algebra $\mathfrak{d} = \bigoplus_{i=2-d}^1 \mathfrak{d}_i$, now concentrated in degrees $\{2-d,\ldots,1\}$ (where d is the dimension of spacetime Σ). Let us write the homotopy Manin action as

$$\int_{\Sigma} \Theta(\mathbb{A}) + \frac{1}{2} \langle \mathbb{A}, d\mathbb{A} \rangle + \frac{1}{2} \langle \mathbb{A}, \star M \mathbb{A} \rangle , \qquad (60)$$

where

- 1. A is a polyform whose p-form component is valued in \mathfrak{d}_{1-p} ; 0
- 2. $\Theta(\mathbb{A})$ is the contribution to the action from the target-space L_{∞} brackets, and thus involves no derivatives of \mathbb{A} ; and
- 3. we have set all antifields, ghosts, etc to zero.

For the Hamiltonian formulation, we split the field \mathbb{A} into time and space components:

$$\mathbb{A} = \mathrm{d} x^0 \mathbb{A}_0 + \mathbb{A}_\Xi \,, \qquad \iota_{\partial_0} \mathbb{A}_0 = \iota_{\partial_0} \mathbb{A}_\Xi = 0 \,, \qquad \mathrm{d} \mathbb{A} = \mathrm{d} x^0 \wedge \dot{\mathbb{A}}_\Xi + \mathrm{d}_\Xi \, \mathbb{A}_\Xi - \mathrm{d} x^0 \wedge \mathrm{d}_\Xi \, \mathbb{A}_0, \tag{61}$$

where spacetime Σ is also split into time and space as $\Sigma = \mathbb{R} \times \Xi$ as a product of (pseudo-)Riemannian manifolds (hence $g^{0i} = 0$) and x^0 runs along \mathbb{R} , and ι denotes the interior product, and denotes derivative along x^0 . (In fact everything below is also valid locally up to integration by parts.) To ensure positivity we will make the additional assumption that $\langle \bullet, M \bullet \rangle |_{\mathfrak{e}} > 0$, where \mathfrak{e} , to be defined below, is a complement to ker M.

First, we evaluate the term involving derivatives:

$$\int_{\Sigma} \eta \left(\mathbb{A} d\mathbb{A} \right) = \int_{\Sigma} \eta \left(2 dx^0 \mathbb{A}_0 d_{\Xi} \, \mathbb{A}_{\Xi} + \mathbb{A}_{\Xi} \, dx^0 \dot{\mathbb{A}}_{\Xi} \right), \tag{62}$$

from which we see that \mathbb{A}_{Σ} together are the positions and momenta, while \mathbb{A}_0 appears linearly. In fact \mathbb{A}_0 will appear linearly also in $\Theta(\mathbb{A})$ (because it must be linear in $\mathrm{d}x^0$) but it appears quadratically in the mass term:

$$\Theta(\mathbb{A}) = \mathrm{d}x^{0} \wedge \mathbb{A}_{0} \wedge \mathbb{G}',
\frac{1}{2}\eta((M\mathbb{A}) \wedge \star \mathbb{A}) = \frac{1}{2}\eta \begin{pmatrix} \mathrm{d}x^{0} \wedge M\mathbb{A}_{0} \wedge \star \left(\mathrm{d}x^{0} \wedge \mathbb{A}_{0}\right) + M\mathbb{A}_{\Xi} \wedge \star \mathbb{A}_{\Xi} \\
+ \underbrace{2\mathrm{d}x^{0} \wedge M\mathbb{A}_{0} \wedge \star \mathbb{A}_{\Xi}}_{=0} \end{pmatrix}.$$
(63)

Here \mathbb{G}' (which depends on \mathbb{A}_{Ξ}) is part of the Gauss law constraint for the AKSZ sigma model and is defined by the above formula; the last term in the second equation may be seen to vanish by linear algebra due to the fact that spacetime is a direct product $\Sigma = \mathbb{R} \times \Xi$ — if the $\mathrm{d} x^{\mu}$ are e.g. orthonormal, $\star \mathbb{A}_{\Sigma}$ will contain $\mathrm{d} x^0$ and thus $\mathrm{d} x^0 \star \mathbb{A}_{\Sigma} = 0$.

Let us now introduce another split:

$$\mathfrak{d} = \ker M + \mathfrak{e}; \qquad \mathbb{A}_0 = \underbrace{\mathbb{L}_0}_{\in \ker M} + \underbrace{\mathbb{E}_0}_{\in \mathfrak{e}}, \tag{64}$$

where \mathfrak{e} is any Lagrangian complement of \mathfrak{g} in \mathfrak{d} , which may be identified with \mathfrak{g}^* . (We do not split \mathbb{A}_{Ξ} this way.) Then the action takes the form

$$S = \int_{\Sigma} \left\langle \mathbb{A}_{\Xi} \wedge dx^{0} \wedge \dot{\mathbb{A}}_{\Xi} + dx^{0} \left(\mathbb{L}_{0} + \mathbb{E}_{0} \right) \wedge \mathbb{G} + \frac{1}{2} \left(M \mathbb{A}_{\Xi} \right) \wedge \star \mathbb{A}_{\Xi} \right.$$
$$\left. + \frac{1}{2} dx^{0} \wedge \left(M \mathbb{E}_{0} \right) \wedge \star \left(dx^{0} \wedge \mathbb{E}_{0} \right) \right\rangle$$
(65)

with $\mathbb{G} := \mathbb{G}' + 2d_{\Xi} \wedge \mathbb{A}_{\Xi}$ being the AKSZ model Gauss law constraint; it depends only on \mathbb{A}_{Ξ} .

The fields to be varied in the action are now \mathbb{A}_{Σ} , \mathbb{L}_0 and \mathbb{E}_0 . Of these, \mathbb{L}_0 is a Lagrange multiplier enforcing certain components of the AKSZ sigma model Gauss law. Since im $M = \mathfrak{g} = \ker M$, we see that $\langle M \bullet, \bullet \rangle|_{\mathfrak{e}}$ is nondegenerate, and \mathbb{E}_0 may be integrated out algebraically. To do this we need the identity

$$\langle dx^0(M\mathbb{E}_0), \star (dx^0\mathbb{E}_0) \rangle = g^{00} \langle M\mathbb{E}_0 , \star \mathbb{E}_0 \rangle, \tag{66}$$

which is best obtained in index notation. (We have also started omitting wedges where unambiguous.) The positivity of the Hamiltonian now follows along the same lines as for 3d Manin theories [15, §2.3] from the following completing-the-square calculation.

We will be more explicit to account for our compact notation: The term linear in \mathbb{E}_0 can be rewritten using index notation and the identification $\mathfrak{e} \cong \mathfrak{g}^*$ facilitated by η as

$$\langle \mathrm{d}x^0 \wedge \mathbb{E}_0 \mathbb{G} \rangle = \mathrm{d}x^0 \wedge \mathbb{E}_{0a} \mathbb{G}^a \tag{67}$$

In this basis, \mathbb{G}^a are *half* the components of \mathbb{G}^a , the other half being \mathbb{G}_a and appearing contracted with the Lagrange multiplier \mathbb{L}_0 . Moreover, we have $\langle M\mathbb{X}, \mathbb{Y} \rangle = M^{ab}\mathbb{X}_a\mathbb{Y}_b$. Since M is nondegenerate when restricted on \mathfrak{e} (by the definition of \mathfrak{e}), M^{ab} is invertible (and symmetric), and in particular may be used for index gymnastics. Therefore we may introduce a \mathfrak{e} -valued polyform C in place of \mathbb{G}^a by

$$\mathrm{d}x^0 \wedge \mathbb{E}_{0a} \mathbb{G}^a \equiv \langle M \mathbb{E}_0 \, \hat{,} \star C \rangle \,. \tag{68}$$

The bilinear form $\langle M \bullet \ \hat{,} \ \star \bullet \rangle$ is symmetric and nondegenerate on ϵ -valued polyforms so we can now complete the square in \mathbb{E}_0 . The complete result for the Hamiltonian (density) is thus

$$\frac{1}{2} (M \mathbb{A}_{\Xi}) \wedge \star \mathbb{A}_{\Xi} - \frac{1}{2} (g^{00})^{-1} \langle MC \, \hat{,} \, \star C \rangle \tag{69}$$

which is manifestly positive definite whenever M^{ab} is (since $g^{00} < 0$).

4. Examples

Let us discuss particular examples of the class of homotopy Manin theories constructed above.

4.1. General classes of examples

First, we list those examples that can be defined in an arbitrary number of spacetime (or world-volume) dimensions.

Example 9 (first-order Yang–Mills theory). Let $\mathfrak g$ be a Lie algebra. Then $(\mathfrak d,\mathfrak g)$ is a Manin pair, where

$$\mathfrak{d} = \mathfrak{g}^* \left[n - 3 \right] \oplus \mathfrak{g} \tag{70}$$

carries Lie bracket

$$[x,y]_{\mathfrak{d}} = [x,y]_{\mathfrak{g}}$$
 $[x,\tilde{x}]_{\mathfrak{d}} = \operatorname{coad}_{x}(\tilde{x})$ $[\tilde{x},\tilde{y}] = 0$ (71)

for $x, y \in \mathfrak{g}$ and $\tilde{x}, \tilde{y} \in \mathfrak{g}^*[n-3]$, where coad is the coadjoint representation.

Suppose that $\kappa \colon \mathfrak{g} \otimes \mathfrak{g} \to \mathbb{R}$ is an invariant metric on \mathfrak{g} , which induces the musical isomorphism

$$\varkappa^{\sharp} \colon \mathfrak{g} \to \mathfrak{g}^{*} \tag{72}$$

$$x \mapsto \kappa(x, -)$$
. (73)

Then

$$M: \mathfrak{d} \to \mathfrak{d}$$
 (74)

$$(x \oplus \tilde{x}[n-3]) \mapsto (\varkappa^{\sharp})^{-1}(\tilde{x}) \tag{75}$$

(for any $x \in \mathfrak{g}$, $\tilde{x} \in \mathfrak{g}^*$) is a Hodge structure on $(\mathfrak{d}, \mathfrak{g})$.

Given a d-dimensional oriented (pseudo-)Riemannian manifold Σ , then

$$\Omega(\Sigma) \otimes \mathfrak{d} = \Omega(\Sigma) \otimes \mathfrak{g} \oplus (\Omega(\Sigma) \otimes \mathfrak{g}^*) [d-3].$$

The subquotient $\hat{\Omega}(\Sigma; \mathfrak{d}, \mathfrak{g})$ may be identified with the subspace of $\Omega(\Sigma; \mathfrak{d})$ that excludes the following:

- elements of the form $\alpha \otimes x$ where $\alpha \in \Omega^p$ and $x \in \mathfrak{g}^*[d-3]$ and $p-d+3 \leqslant 0$ (such elements do not lie in $\tilde{\Omega}(\Sigma; \mathfrak{d}, \mathfrak{g})$)
- elements of the form $\alpha \otimes x$ where $\alpha \in \Omega^p$ and $x \in \mathfrak{g}$ and $p \geqslant 3$ (such elements lie in $\check{\Omega}(\Sigma; \mathfrak{g})$).

That is, we may identify

$$\hat{\Omega}(\Sigma; \mathfrak{d}, \mathfrak{g}) \cong \underbrace{\Omega^{0}(\Sigma; \mathfrak{g}) \oplus \Omega^{1}(\Sigma; \mathfrak{g}) \oplus \Omega^{d-2}(\Sigma; \mathfrak{g}^{*}[d-3])}_{ghost}$$

$$\oplus \underbrace{\Omega^{d-1}(\Sigma; \mathfrak{g}^{*}[d-3]) \oplus \Omega^{2}(\Sigma; \mathfrak{g}) \oplus \Omega^{d}(\Sigma; \mathfrak{g}^{*}[d-3]),}_{A^{+}}$$

$$\oplus \underbrace{\Omega^{d-1}(\Sigma; \mathfrak{g}^{*}[d-3]) \oplus \Omega^{2}(\Sigma; \mathfrak{g}) \oplus \Omega^{d}(\Sigma; \mathfrak{g}^{*}[d-3]),}_{ghost antifield}$$
(76)

which agrees with the field content for first-order Yang-Mills theory. The associated hMC action is

$$S_{\hat{\Omega}(\Sigma;\mathfrak{d},\mathfrak{g})} = \int_{\Sigma} B \wedge \left(dA + \frac{1}{2} [A, A] \right) + c \left(dA^{+} + A \wedge A^{+} + B \wedge B^{+} \right) + \frac{1}{2} c^{+} [c, c]. \tag{77}$$

The deformation μ_i^M adds an extra quadratic term to the Maurer–Cartan action:

$$S = \int_{\Sigma} B \wedge \left(dA + \frac{1}{2} [A, A] \right) + \frac{1}{2} t B \wedge \star B + c \left(dA^{+} + A \wedge A^{+} + B \wedge B^{+} \right) + \frac{1}{2} c^{+} [c, c], \tag{78}$$

where we may set t = 1 (or absorb it into B), which yields the usual action for first-order Yang–Mills theory (see e.g. [37], [29, §5.4]).

Example 10 (ordinary sigma model). Let (Σ, g) be an (n+1)-dimensional pseudo-Riemannian manifold (worldvolume), and let Y be a smooth manifold (target space). Define the shifted cotangent bundle

$$X := T^* [n] Y \xrightarrow{p} Y \tag{79}$$

with vanishing homological vector field Q = 0 and the canonical symplectic structure is a symplectic n-algebroid. The corresponding AKSZ theory is given by the action

$$S = \int_{\Sigma} A_i \wedge \mathrm{d}\phi^i \tag{80}$$

where $\phi \in \Omega^0(\Sigma; Y)$ and $A \in \Omega^n(\Sigma; \phi^*T^*Y)$ and d is the derivative of a smooth map between manifolds so that $d\phi \in \Omega^1(\Sigma; \phi^*TY)$. This is a trivial theory describing a constant ϕ and closed A

Fix a pseudo-Riemannian metric M_{ij} on Y. Then the Levi–Civita connection on TY induces a canonical Ehresmann connection

$$TX = V_p \oplus H \tag{81}$$

on TX, where $p: X \to Y$ is the canonical projection. Then (p, H) is an admissible fibration, and a Hodge structure on it is given by the inverse Riemannian metric M^{ij} . The corresponding homotopy Manin theory is

$$S = \int_{\Sigma} A_i \wedge d\phi^i - \frac{1}{2} M^{ij} A_i \wedge \star A_j. \tag{82}$$

The equation of motion for A is now

$$A_i = \star^{-1} M_{ii} \mathrm{d}\phi^i. \tag{83}$$

Integrating out A, we obtain

$$S = \frac{1}{2} \int_{\Sigma} M_{ij} \left(\star^{-1} d\phi^{i} \right) \wedge d\phi^{i}, \tag{84}$$

which is the action for the ordinary sigma model on the Riemannian manifold (X, M).

Example 11 (Freedman–Townsend form of principal chiral model). Let $\mathfrak g$ be a Lie algebra. Then $(\mathfrak d,\mathfrak g^*[d-3])$ is a Manin pair, where

$$\mathfrak{d} = \mathfrak{g}^* \left[d - 3 \right] \oplus \mathfrak{g} \tag{85}$$

carries Lie bracket

$$[x,y]_{\mathfrak{d}} = [x,y]_{\mathfrak{g}}$$
 $[x,\tilde{x}]_{\mathfrak{d}} = \operatorname{coad}_{x}(\tilde{x})$ $[\tilde{x},\tilde{y}] = 0$ (86)

for $x, y \in \mathfrak{g}$ and $\tilde{x}, \tilde{y} \in \mathfrak{g}^*[d-3]$, where coad is the coadjoint representation.

Suppose that $\kappa \colon \mathfrak{g} \otimes \mathfrak{g} \to \mathbb{R}$ is an invariant metric on \mathfrak{g} , which by musical isomorphism induces an isomorphism

$$\chi^{\sharp} \colon \mathfrak{g} \to \mathfrak{g}^*$$
(87)

$$x \mapsto \kappa(x, -)$$
. (88)

Then

$$M: \mathfrak{d} \to \mathfrak{d}$$
 (89)

$$(x \oplus \tilde{x}[d-3]) \mapsto (0 \oplus \varkappa^{\sharp}(x)) \tag{90}$$

(for any $x \in \mathfrak{g}$, $\tilde{x} \in \mathfrak{g}^*$) is a Hodge structure on $(\mathfrak{d}, \mathfrak{g}^*[d-3])$.

The corresponding homotopy Manin theory on an n-dimensional (pseudo-)Riemannian manifold Σ has field content

$$\underbrace{\Omega^{0}\left(\Sigma; \mathfrak{g}^{*}\left[d-3\right]\right) \oplus \cdots \oplus \Omega^{d-3}\left(\Sigma; \mathfrak{g}^{*}\left[d-3\right]\right)}_{c^{(d-3)}} \underbrace{\Theta^{0}\left(\Sigma; \mathfrak{g}^{*}\left[d-3\right]\right)}_{c^{(d-3)}} \underbrace{\Theta^{0}\left(\Sigma; \mathfrak{g}^{*}\left[d-3\right]\right) \oplus \Omega^{n-1}\left(\Sigma; \mathfrak{g}^{*}\left[d-3\right]\right) \oplus \Omega^{2}\left(\Sigma; \mathfrak{g}^{*}\left[d-3\right]\right)}_{c^{(d-1)+}=:A} \underbrace{\Theta^{0}\left(\Sigma; \mathfrak{g}^{*}\left[d-3\right]\right) \oplus \Omega^{n-1}\left(\Sigma; \mathfrak{g}^{*}\left[d-3\right]\right) \oplus \Omega^{2}\left(\Sigma; \mathfrak{g}^{*}\left[d-3\right]\right)}_{c^{(d-1)+}=:B^{+}} \underbrace{\Theta^{0}\left(\Sigma; \mathfrak{g}^{*}\left[d-3\right]\right) \oplus \Omega^{0}\left(\Sigma; \mathfrak{g}^{*}\left[d-3\right]\right)}_{c^{(d-1)+}=:B^{+}} \underbrace{\Theta^{0}\left(\Sigma; \mathfrak{g}^{*}\left[d-3\right]\right)}_{c^{(d$$

The corresponding action is the Freedman–Townsend formulation [38, 39] of the principal chiral model:

$$S = \int_{\Sigma} \operatorname{tr} \left(\frac{1}{2} A \wedge \star A + \sum_{i=0}^{d-2} c^{(i)} \wedge dc^{(i+1)+} + \sum_{i,j} c^{(i+j)} \wedge c^{+(i)} \wedge c^{+(j)} \right). \tag{92}$$

Amongst these terms, the terms involving at most one field not of degrees 1 or 2 are

$$S = \int_{\Sigma} \operatorname{tr}\left(B \wedge \left(dA + \frac{1}{2}[A, A]\right) + \frac{1}{2}A \wedge \star A + c^{(d-3)} \wedge (d + A \wedge) B^{+} + \frac{1}{2}B^{+} \wedge B^{+} \wedge c^{(d-4)}\right) + \cdots$$
(93)

The field B enforces flatness of A. We can solve this constraint as $A = g^{-1}dg$, so that the action becomes that of the principal chiral model.

Example 12 (Broccoli–Deger–Theisen theory). Suppose that \mathfrak{h}^0 is a Lie algebra, and let V be a vector space. Let

$$\alpha \colon \left(\mathfrak{h}^0\right)^{\wedge i} \to V \tag{94}$$

be a V-valued Lie algebra cocycle. Then

$$\mathfrak{h} := \mathfrak{h}^0 \oplus V[i-1] \tag{95}$$

admits an L_{∞} -algebra structure that is a central extension of \mathfrak{h}^0 . Let us then define

$$\mathfrak{d} = \mathfrak{h}^0 \oplus V[i-1] \oplus V^*[d-p-2] \oplus (\mathfrak{h}^0)^*[d-3] \tag{96}$$

to be the L_{∞} -algebra in which any bracket vanishes when one or more of the arguments belong to $V^*[d-p-2] \oplus (\mathfrak{h}^0)^*[d-3]$. This admits a canonical cyclic structure. Then

$$\mathfrak{g} = V^* \left[d - p - 2 \right] \oplus \left(\mathfrak{h}^0 \right)^* \left[d - 3 \right] \subset \mathfrak{d} \tag{97}$$

is an Abelian L_{∞} -subalgebra, which is easily seen to be admissible. Further suppose that $\mathfrak g$ admits an invariant inner product, and also equip V with an inner product. A Hodge structure is then given by

$$M \colon \mathfrak{d} \to \mathfrak{d}$$
 (98)

$$\left(\tilde{a},\tilde{b},b,a\right)\mapsto\left(0,0,\tilde{b},\tilde{a}\right)$$
 (99)

where we have implicitly identified \mathfrak{g} with \mathfrak{g}^* and V with V^* , via the musical isomorphisms induced by the inner products on \mathfrak{g} and V. The resulting action is then

$$S = \int \tilde{A} \wedge F[A] + \frac{1}{2} M_{ab} A^a \wedge \star A^a + \tilde{B} \wedge (dB + A \wedge \dots \wedge A) + \frac{1}{2} M_{ij} B^i \wedge \star B^j, \tag{100}$$

where the field content is

$$A \in \Omega^1(M; \mathfrak{g}) \tag{101}$$

$$B \in \Omega^p(M; \mathfrak{h}) \tag{102}$$

$$\tilde{B} \in \Omega^{d-p-1}(M; \mathfrak{h}^*) \tag{103}$$

$$\tilde{A} \in \Omega^{d-2}(M; \mathfrak{g}^*). \tag{104}$$

The equations of motion are then

$$dB + A \wedge \dots \wedge A = 0 \tag{105}$$

$$\mathrm{d}\tilde{B}_i + M_{ii} \star B^i = 0 \tag{106}$$

$$dA + A \wedge A = 0 \tag{107}$$

$$d\tilde{A}_a + M_{ab} \star A^i = 0, (108)$$

which reproduces the equations in [40, §3].

4.2. Two dimensions

A Lie 1-algebroid is the same as a Lie algebroid $\mathfrak{d} \to Y$, and a symplectic Lie (1-)algebroid (the target space for a one-dimensional AKSZ sigma model) is the same as a Poisson manifold (Y,π) , or rather the associated cotangent Lie algebroid $X:=T^*_{\pi}[1]Y$, whose underlying vector bundle is the cotangent bundle $T^*[1]Y$ and whose anchor is given by $\pi^{\sharp}: T^*Y \to TY$, and the symplectic form is the canonical pairing between $T^*[1]Y$ and TY.

The AKSZ sigma model in two dimensions is the Poisson sigma model [41–43] (reviewed in [44, 45]), given by

$$S = \int_{\Sigma} A_i \wedge d\phi^i - \frac{1}{2} \pi^{ij} A_i \wedge A_j \tag{109}$$

for $\phi \in \Omega^0(\Sigma; Y)$ and $A \in \Omega^1(\Sigma; \phi^*T^*Y)$.

Example 13. Given a Poisson manifold (Y,π) with a Riemannian metric M_{ij} on Y, we have the admissible fibration

$$\mathbf{T}_{\pi}^{*}\left[1\right]Y \to Y \tag{110}$$

of the cotangent Lie algebroid $X := T_{\pi}^*[1]Y$ together with an Ehresmann connection corresponding to the Levi–Civita connection of M. A Hodge structure on this is given by the inverse Riemannian metric M^{ij} .

The action of the homotopy Manin theory is

$$S = \int_{\Sigma} A_i \wedge d\phi^i - \frac{1}{2} \pi^{ij} A_i \wedge A_j - \frac{1}{2} M^{ij} A_i \wedge \star A_j$$
 (111)

This action is not quite invariant under the full Lie algebroid gauge symmetry

$$\delta \phi^{i} = -\pi^{ij} \epsilon_{j} \qquad \delta A_{\mu i} = A_{\mu i} + \partial_{\mu} \alpha_{i} + \frac{1}{2} \partial_{i} \pi^{j k} A_{\mu j} \alpha_{k}$$
 (112)

for $\alpha \in \Omega^0(\Sigma, \phi^*T^*X)$ due to the mass term.

Now, we can integrate out A as

$$A_i = \left(M^{\sharp} + \star \pi^{\sharp}\right)^{-1}{}_{ij}\mathrm{d}\phi^j,\tag{113}$$

where $M^{\sharp}: T^*Y \to TY$ is induced by the Riemannian metric M, so that

$$S = \int_{\Sigma} g_{ij} d\phi^{i} \wedge \left(M^{\sharp} + \star \pi^{\sharp} \right)^{-1}{}_{ij} \star d\phi^{j}$$
(114)

Example 14. Let (Y, π) be a linear Poisson manifold, i.e. a Lie coalgebra, and let $X := T_{\pi}^*[1]Y$. Then we have the admissible fibration consisting of the graded vector bundle

$$T^* [1] Y \cong Y \times Y^* [1] \longrightarrow Y^* [1] \tag{115}$$

equipped with the trivial Ehresmann connection. A Hodge structure is given by a nondegenerate bilinear metric M on X. Then the action is

$$S = \int_{\Sigma} A_i \wedge d\phi^i - \frac{1}{2} \pi^{ij} A_i \wedge A_j - \frac{1}{2} M_{ij} \phi^i \wedge \star \phi^j$$
(116)

for $\phi \in \Omega^0(\Sigma) \otimes X$ and $A \in \Omega^1(\Sigma) \otimes X$. We can integrate out ϕ as

$$\phi^i = M^{ij} \star dA_i \tag{117}$$

so that

$$S = \int_{\Sigma} \frac{1}{2} M^{ij} dA_i \wedge \star dA_j - \frac{1}{2} \pi^{ij} A_i \wedge A_j.$$
(118)

This theory contains two-dimensional Maxwell theory as the special case where Y is a one-point space. In the general case, the theory describes a deformation of a $U(1)^n$ gauge theory, which is reminiscent of the Proca theory.

4.2.1. Yang-Baxter sigma models. Yang-Baxter sigma models [16, 17] (reviewed in [18, 19]), which are integrable deformations of the principal chiral model or sigma models on symmetric spaces, may be naturally realised as homotopy Manin theories on Poisson-Lie groups [46, 47] (reviewed in [48, 49]).

Let (G, π) be a Poisson–Lie group whose Lie algebra is \mathfrak{g} , so that $X := T_{\pi}^*[1]G$. The Poisson structure of G induces a Lie bialgebra structure on \mathfrak{g} . The corresponding Poisson sigma model is

$$S = \int_{\Sigma} \operatorname{tr}\left(g^{-1} dg \wedge A\right) - \frac{1}{2} \pi^{\sharp} \left(A \wedge A\right),\tag{119}$$

where $g \in \Omega^0(\Sigma; G)$ and $A \in \Omega^1(\Sigma; \mathfrak{g}^*)$. An admissible fibration on this Poisson–Lie group is given by the vector bundle $X = T_\pi^*[1]G \twoheadrightarrow G$ together with the canonical Ehresmann connection given by the canonical trivialisation $T^*[1]G \cong G \times \mathfrak{g}^*[1]$. A Hodge structure (metric) is given by the choice of an invariant metric on \mathfrak{g} . Using this, we can deform the Poisson sigma model to

$$S = \int_{\Sigma} \operatorname{tr}\left(g^{-1} dg \wedge A\right) - \frac{1}{2} \pi^{\sharp} \left(A \wedge A\right) - \frac{1}{2} A \wedge \star A. \tag{120}$$

The equation of motion for A is

$$A + \star \pi^{\sharp}(A, -) = \star g^{-1} \mathrm{d}g. \tag{121}$$

So, integrating A out, we obtain

$$S = \int_{\Sigma} \operatorname{tr}\left(g^{-1} dg \left(1 + \star \pi^{\sharp}\right)^{-1} \wedge \star g^{-1} dg\right), \tag{122}$$

which is seen to be the action for the Yang-Baxter sigma model.

4.3. Three dimensions

A symplectic Lie 2-algebra is equivalent to a Courant algebroid [50, 51]. Specifically, a Courant algebroid $(E \rightarrow X, \langle , \rangle, [,])$ corresponds to a symplectic Lie two-algebroid

$$T^*[2]X \oplus E[1] \twoheadrightarrow X. \tag{123}$$

Picking local coordinates, we have the action

$$S = \int_{\Sigma} D\phi \wedge B + A \wedge dA + A \wedge A \wedge A + B \wedge \rho(A). \tag{124}$$

A Courant algebroid over a single point is the same as a Lie algebra $\mathfrak d$ with an invariant metric. In this case, the corresponding AKSZ theory is (three-dimensional) Chern–Simons theory

$$\int_{\Sigma} \operatorname{tr}\left(A \wedge dA + \frac{2}{3}A \wedge A \wedge A\right) \tag{125}$$

for $A \in \Omega^1(\Sigma; \mathfrak{d})$. A choice of a Manin pair $\mathfrak{g} \subset \mathfrak{d}$ and a Hodge structure $M \colon \mathfrak{d}/\mathfrak{g} \to \mathfrak{g}$ leads to the action

$$\int_{\Sigma} \operatorname{tr}\left(A \wedge dA + \frac{2}{3}A \wedge A \wedge A\right) + A \wedge \star MA,\tag{126}$$

which is the Manin theory [15].

Data availability statement

No new data were created or analysed in this study.

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